



Incremental Techniques for Large-Scale Dynamic Query Processing

Tutorial

Part 2

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Outline

- Part I: Introduction
- Part II: Main Algorithmic Ideas in Dynamic Query Processing: Traditional IVM and Recent Advances
- Part III: Generalizations to Arbitrary Ring Structures
 - Part IV: Dynamic Query Processing in Big Data Frameworks
 - Part V: Outlook

Generalisation to Arbitrary Ring Structures

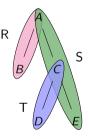
- ullet The IVM machinery presented so far uses the ring over $\mathbb Z$
 - ⇒ Tuples are mapped to integers.
 - ⇒ Query operators use addition and multiplication.
- This ring suffices to compute and maintain the count aggregate.
- However, more complex analytical tasks might require other rings.
- Now, we present Factorized IVM (F-IVM) that allows for task-specific rings.
 - ⇒ The machinery for maintenance remains the same.
 - ⇒ Different applications are captured by different rings.

Incremental View Maintenance with Triple Lock Factorization Benefits.

Milos Nikolic and Dan Olteanu. SIGMOD 2018

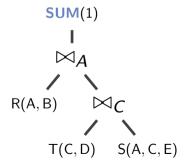
Compute COUNT over the natural join: R(a,b), S(a,c,e), T(c,d)

```
Q = SELECT SUM(1)
FROM R NATURAL JOIN S
NATURAL JOIN T
```



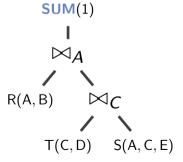
Naïve: compute the join and then SUM(1)

```
Q = SELECT SUM(1)
FROM R NATURAL JOIN S
NATURAL JOIN T
```



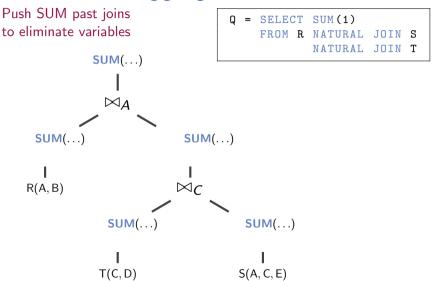
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Q = SELECT SUM(1)
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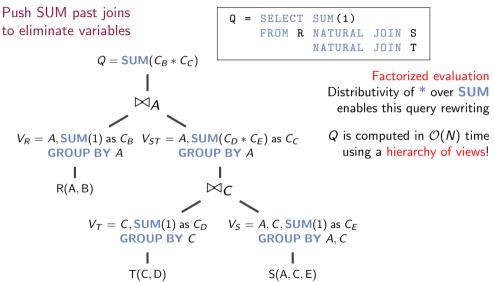


Let all relations be of size N

Computing Q takes $\mathcal{O}(N^3)$ time!



```
Push SUM past joins
                                          = SELECT
                                                     SUM (1)
to eliminate variables
                                                      NATURAL
                                                                JOIN T
                Q = SUM(C_R * C_C)
                      \bowtie_{\mathcal{A}}
  V_R = A, SUM(1) as C_B V_{ST} = A, SUM(C_D * C_E) as C_C
        GROUP BY A
                       GROUP BY A
         R(A, B)
              V_T = C, SUM(1) as C_D V_S = A, C, SUM(1) as C_E
                    GROUP BY C
                                            GROUP BY A. C
                      T(C, D)
                                              S(A, C, E)
```

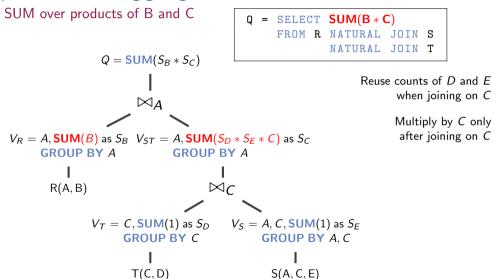


Example: SUM Aggregate

SUM over products of B and C

```
Q = SELECT SUM(B * C)
FROM R NATURAL JOIN S
NATURAL JOIN T
```

Example: SUM Aggregate



```
SELECT SUM (g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
              FROM R. NATURAL, JOIN S. NATURAL, JOIN T.
             Q = SUM(S_B * S_C * g_A(A))
V_R = A, SUM(g_B(B)) as S_B V_{ST} = A, SUM(S_D * S_E * g_C(C)) as S_C
     GROUP BY A
                                  GROUP BY A
         R(A, B)
                                           \bowtie_{\mathcal{C}}
            V_T = C, SUM(g_D(D)) as S_D 	 V_S = A, C, SUM(g_E(E)) as S_E
                  GROUP BY C
                                               GROUP BY A. C.
                      T(C, D)
                                                   S(A, C, E)
```

```
SELECT SUM (g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
              FROM R NATURAL JOIN S NATURAL JOIN T
             Q = SUM(S_B * S_C * g_A(A))
                                                             Join on & eliminate
                                                            one variable at a time
V_R = A, SUM(g_B(B)) as S_B V_{ST} = A, SUM(S_D * S_E * g_C(C)) as S_C
     GROUP BY A
                                  GROUP BY A
                                           \bowtie_{\mathcal{C}}
         R(A, B)
            V_T = C, SUM(g_D(D)) as S_D 	 V_S = A, C, SUM(g_E(E)) as S_E
                  GROUP BY C
                                               GROUP BY A. C.
                           eliminate D
                      T(C, D)
                                                   S(A, C, E)
```

```
SELECT SUM (g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
              FROM R NATURAL JOIN S NATURAL JOIN T
            Q = SUM(S_B * S_C * g_A(A))
                                                           Join on & eliminate
                                                         one variable at a time
V_R = A, SUM(g_B(B)) as S_B V_{ST} = A, SUM(S_D * S_E * g_C(C)) as S_C
     GROUP BY A
                                GROUP BY A
         R(A, B)
           V_T = C, SUM(g_D(D)) as S_D 	 V_S = A, C, SUM(g_E(E)) as S_E
                 GROUP BY C
                                             GROUP BY A. C.
                          eliminate D
                                                       eliminate E
                     T(C, D)
                                                 S(A, C, E)
```

```
SELECT SUM (g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
              FROM R NATURAL JOIN S NATURAL JOIN T
             Q = SUM(S_B * S_C * g_A(A))
                                                             Join on & eliminate
                                                            one variable at a time
V_R = A, SUM(g_B(B)) as S_B V_{ST} = A, SUM(S_D * S_E * g_C(C)) as S_C
     GROUP BY A
                                  GROUP BY A
                                                eliminate C
                                           \bowtie_{\mathcal{C}}
         R(A, B)
            V_T = C, SUM(g_D(D)) as S_D 	 V_S = A, C, SUM(g_E(E)) as S_E
                  GROUP BY C
                                               GROUP BY A. C.
                           eliminate D
                                                          eliminate E
                      T(C, D)
                                                   S(A, C, E)
```

```
SELECT SUM (g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
              FROM R NATURAL JOIN S NATURAL JOIN T
             Q = SUM(S_B * S_C * g_A(A))
                                                             Join on & eliminate
                                                            one variable at a time
V_R = A, SUM(g_B(B)) as S_B V_{ST} = A, SUM(S_D * S_E * g_C(C)) as S_C
     GROUP BY A
                                  GROUP BY A
               eliminate B
                                                eliminate C
                                           \bowtie_{\mathcal{C}}
         R(A, B)
            V_T = C, SUM(g_D(D)) as S_D 	 V_S = A, C, SUM(g_E(E)) as S_E
                  GROUP BY C
                                               GROUP BY A. C.
                           eliminate D
                                                         eliminate E
                      T(C, D)
                                                   S(A, C, E)
```

```
SELECT SUM (g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
               FROM R NATURAL JOIN S NATURAL JOIN T
              Q = SUM(S_B * S_C * g_A(A))
                                                                Join on & eliminate
                             eliminate A
                                                              one variable at a time
                        \bowtie_{\mathcal{A}}
V_R = A, SUM(g_B(B)) as S_B V_{ST} = A, SUM(S_D * S_E * g_C(C)) as S_C
      GROUP BY A
                                   GROUP BY A
               eliminate B
                                                 eliminate C
                                            \bowtie_{\mathcal{C}}
          R(A, B)
            V_T = C, SUM(g_D(D)) as S_D 	 V_S = A, C, SUM(g_E(E)) as S_E
                   GROUP BY C
                                                 GROUP BY A. C.
                            eliminate D
                                                            eliminate E
                       T(C, D)
                                                     S(A, C, E)
```

```
Q = SELECT SUM(g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
FROM R NATURAL JOIN S NATURAL JOIN T
```

Imagine aggregate values are of type ${\mathcal R}$

$$g_X:\mathsf{Dom}(X) o\mathcal{R}$$

Can we evaluate Q using the query plan from before?

Yes(!), but we need to:

- Define the binary operators * and + in ${\cal R}$
- Define zero in \mathcal{R} (for initial values)
- Define one in \mathcal{R} (e.g., if X is not used, $g_X(x) = 1$)
- Ensure distributivity of * over +

Rings

• A ring $(\mathcal{R}, +, *, \mathbf{0}, \mathbf{1})$ is a set \mathcal{R} with two binary operators: Additive commutativity a + b = b + aAdditive associativity (a + b) + c = a + (b + c)Additive identity $\mathbf{0} + a = a + \mathbf{0} = a$ Additive inverse $\exists -a \in \mathcal{R} : a + (-a) = (-a) + a = \mathbf{0}$ Multiplicative associativity (a*b)*c = a*(b*c)Multiplicative identity a * 1 = 1 * a = aLeft and right distributivity a*(b+c) = a*b+a*c and (a + b) * c = a * c + b * c

Examples: $\mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}, \mathbb{R}^n$, matrix ring, polynomial ring

Factorized Ring Computation

- Relations are functions
 - mapping keys (tuples) to payloads (ring elements)

Α	В	\rightarrow	R[<i>A</i> , <i>B</i>]	
a ₁ a ₂	$b_1 \\ b_1$	$\overset{\rightarrow}{\rightarrow}$	r ₁ r ₂	

Finitely many tuples with non-zero payloads

 r_1 and r_2 are elements from a ring

- Query language
 - Operations: union, join, and variable marginalization
 - More expressiveness via application-specific rings
- Query evaluation
 - using view trees as shown before

More General SUM Aggregate

```
Q = SELECT SUM(g_A(A) * g_B(B) * g_C(C) * g_D(D) * g_E(E))
FROM R NATURAL JOIN S NATURAL JOIN T
```

Expressed in our framework:

$$Q = \bigoplus_{A \bigoplus_{B} \bigoplus_{C} \bigoplus_{D} \bigoplus_{E}} (\underbrace{R[A,B] \otimes S[A,C,E] \otimes T[C,D]}_{natural\ joins})$$

Intuition: Relation payloads carry out the summation!

Marginalization of X applies g_X , sums payloads, projects away X Join multiplies payloads of matching tuples

Relations R, S, and T with payloads from a ring $(\mathcal{R}, +, *, \mathbf{0}, \mathbf{1})$:

Α	В	\rightarrow	R[A, B]
a ₁ a ₂	$b_1 \\ b_1$	$\overset{\rightarrow}{\rightarrow}$	r ₁ r ₂

$$\begin{array}{ccccc}
A & B & \rightarrow & S[A,B] \\
a_2 & b_1 & \rightarrow & s_1 \\
a_3 & b_2 & \rightarrow & s_2
\end{array}$$

$$\begin{array}{cccc} \mathsf{B} & \mathsf{C} & \to & \mathsf{T}[B,C] \\ \hline b_1 & c_1 & \to & t_1 \\ b_2 & c_2 & \to & t_2 \\ \end{array}$$

Relations R, S, and T with payloads from a ring $(\mathcal{R}, +, *, \mathbf{0}, \mathbf{1})$:

$$\begin{array}{ccccc} A & B & \rightarrow & R[A,B] \\ \hline a_1 & b_1 & \rightarrow & r_1 \\ a_2 & b_1 & \rightarrow & r_2 \\ \end{array}$$

$$\begin{array}{cccc} A & B & \rightarrow & S[A,B] \\ \hline a_2 & b_1 & \rightarrow & s_1 \\ a_3 & b_2 & \rightarrow & s_2 \end{array}$$

$$\begin{array}{cccc} \mathsf{B} & \mathsf{C} & \to & \mathsf{T}[B,C] \\ \hline b_1 & c_1 & \to & t_1 \\ b_2 & c_2 & \to & t_2 \end{array}$$

Union \uplus

Α	В	\rightarrow	$(R \uplus S)[A, B]$
a ₁ a ₂ a ₃	$\begin{array}{c} b_1 \\ b_1 \\ b_2 \end{array}$	$\begin{array}{c} \rightarrow \\ \rightarrow \\ \rightarrow \end{array}$	$egin{array}{c} r_1 \\ r_2 + s_1 \\ s_2 \end{array}$

Relations R, S, and T with payloads from a ring $(\mathcal{R}, +, *, \mathbf{0}, \mathbf{1})$:

$$\begin{array}{cccc}
A & B & \rightarrow & R[A, B] \\
\hline
a_1 & b_1 & \rightarrow & r_1 \\
a_2 & b_1 & \rightarrow & r_2
\end{array}$$

$$\begin{array}{cccc} A & B & \rightarrow & S[A,B] \\ \hline a_2 & b_1 & \rightarrow & s_1 \\ a_3 & b_2 & \rightarrow & s_2 \\ \end{array}$$

$$\begin{array}{cccc} \mathsf{B} & \mathsf{C} & \to & \mathsf{T}[B,C] \\ b_1 & c_1 & \to & t_1 \\ b_2 & c_2 & \to & t_2 \end{array}$$

Union \uplus

$$\begin{array}{cccc} A & B & \rightarrow & (\mathsf{R} \uplus \mathsf{S})[A,B] \\ \hline a_1 & b_1 & \rightarrow & r_1 \\ a_2 & b_1 & \rightarrow & r_2 + s_1 \\ a_3 & b_2 & \rightarrow & s_2 \\ \end{array}$$

Relations R, S, and T with payloads from a ring $(\mathcal{R},+,*,\boldsymbol{0},\boldsymbol{1})$:

Α	В	\rightarrow	R[A, B]
a ₁ a ₂	$b_1 \\ b_1$	$\overset{\rightarrow}{\rightarrow}$	r_1 r_2

$$\begin{array}{cccc} A & B & \rightarrow & S[A,B] \\ \hline a_2 & b_1 & \rightarrow & s_1 \\ a_3 & b_2 & \rightarrow & s_2 \end{array}$$

$$\begin{array}{cccc} \mathsf{B} & \mathsf{C} & \to & \mathsf{T}[B,C] \\ \hline b_1 & c_1 & \to & t_1 \\ b_2 & c_2 & \to & t_2 \end{array}$$

Union \uplus

Α	В	\rightarrow	$(R \uplus S)[A, B]$
a ₁ a ₂ a ₃	$\begin{array}{c} b_1 \\ b_1 \\ b_2 \end{array}$	$\begin{array}{c} \rightarrow \\ \rightarrow \\ \rightarrow \end{array}$	$r_2 \overset{r_1}{\underset{s_2}{+}} s_1$

$\mathsf{Join} \, \otimes \,$

Α	В	C	\rightarrow	$((R \uplus S) \otimes T)[A,B,C]$
a_2	$\begin{array}{c} b_1 \\ b_1 \\ b_2 \end{array}$	c_1	\rightarrow	$(r_2 + s_1) * t_1 s_2 * t_2$

Relations R, S, and T with payloads from a ring $(\mathcal{R},+,*,\mathbf{0},\mathbf{1})$:

$$\begin{array}{ccccc}
A & B & \rightarrow & S[A, B] \\
\hline
a_2 & b_1 & \rightarrow & s_1 \\
a_3 & b_2 & \rightarrow & s_2
\end{array}$$

Union ⊎

$$\begin{array}{cccc} A & B & \to & (R \uplus S)[A, B] \\ \hline a_1 & b_1 & \to & r_1 \\ a_2 & b_1 & \to & r_2 + s_1 \\ a_3 & b_2 & \to & s_2 \\ \end{array}$$

$\mathsf{Join} \, \otimes \,$

Relations R, S, and T with payloads from a ring $(\mathcal{R}, +, *, \mathbf{0}, \mathbf{1})$:

Α	В	\rightarrow	R[A, B]
a ₁ a ₂	$b_1 \\ b_1$	$\overset{\rightarrow}{\rightarrow}$	r_1 r_2

$$\begin{array}{ccccc}
A & B & \rightarrow & S[A, B] \\
\hline
a_2 & b_1 & \rightarrow & s_1 \\
a_3 & b_2 & \rightarrow & s_2
\end{array}$$

$$\begin{array}{c|cccc} B & C & \rightarrow & T[B,C] \\ \hline b_1 & c_1 & \rightarrow & t_1 \\ b_2 & c_2 & \rightarrow & t_2 \\ \end{array}$$

Union ⊎

Join ⊗

Marginalization \bigoplus_A

for a given
$$g_A: \mathsf{Dom}(A) o \mathcal{R}$$

B C
$$\rightarrow$$
 $(\bigoplus_{A} (R \uplus S) \otimes T)[B, C]$
 $b_1 c_1 \rightarrow r_1 * t_1 * g_A(a_1) + (r_2 + s_1) * t_1 * g_A(a_2)$
 $b_2 c_2 \rightarrow s_2 * t_2 * g_A(a_3)$

General Query Form

```
Q = SELECT X_1, ..., X_f, SUM(\mathbf{g_{f+1}(X_{f+1})} * \cdots * \mathbf{g_m(X_m)})
FROM R_1 NATURAL JOIN ... NATURAL JOIN R_n
GROUP BY X_1, ..., X_f
```

Expressed as Functional Aggregate Query:

$$Q[X_1,\ldots,X_f]=\bigoplus_{X_{f+1}}\ldots\bigoplus_{X_m}\bigotimes_{i\in[n]}\mathsf{R}_i[\mathcal{S}_i]$$

where:

- Relations R_1, \ldots, R_n are defined over variables X_1, \ldots, X_m
- X_1, \ldots, X_f are free variables
- R_i maps keys over schema S_i to payloads in a ring $(\mathcal{R},+,*,\mathbf{0},\mathbf{1})$
- Aggregations $\bigoplus_{X_{f+1}}, \dots, \bigoplus_{X_m}$ use functions $\mathsf{g_{f+1}}, \dots, \mathsf{g_m}$

Applications

A host of problems are captured using task-specific rings

- Group-by aggregation over joins (we've seen this already)
- Gradient computation for learning regression models
- Representation of results of conjunctive queries
- Matrix chain multiplication
- ..

Learning Linear Regression Models

• Find model parameters Θ best satisfying:







• Iterative gradient computation:

$$\Theta_{i+1} = \Theta_i - \alpha \mathbf{X}^T (\mathbf{X} \Theta_i - \mathbf{Y})$$
 (repeat until convergence)

- Matrices X^T X and X^T Y computed once for all iterations
 - Compute $SUM(X_i \cdot X_j)$, $SUM(X_i)$, and SUM(1) for variables X_i and X_i
 - We assume that all variables are continuous

Learning Linear Regression Models over Joins

Compute $X^T X$ where X is the join of the input relations

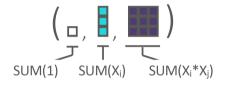
- Naïve: compute the join, then $\mathcal{O}(m^2)$ sums over the join result (m = #query variables)
- Factorized: compute one optimized join-aggregate query
 - Using our running query

$$Q = \bigoplus_{A} \bigoplus_{B} \bigoplus_{C} \bigoplus_{D} \bigoplus_{E} (R[A, B] \otimes S[A, C, E] \otimes T[C, D])$$

but a different payload ring and different functions $g_X!$

Linear Regression Ring

Set
$$\mathcal{R} = (\mathbb{Z}, \mathbb{R}^m, \mathbb{R}^{m \times m})$$
 of triples

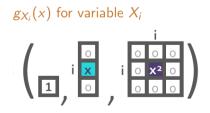


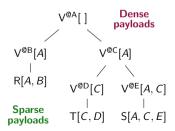
$$a +^{\mathcal{R}} b = (c_a + c_b, \mathbf{s}_a + \mathbf{s}_b, \mathbf{Q}_a + \mathbf{Q}_b)$$

$$a *^{\mathcal{R}} b = (c_a c_b, c_b \mathbf{s}_a + c_a \mathbf{s}_b, c_b \mathbf{Q}_a + c_a \mathbf{Q}_b + \mathbf{s}_a \mathbf{s}_b^T + \mathbf{s}_b \mathbf{s}_a^T)$$

$$\mathbf{0} = (0, \mathbf{0}_{m \times 1}, \mathbf{0}_{m \times m})$$

$$\mathbf{1} = (1, \mathbf{0}_{m \times 1}, \mathbf{0}_{m \times m})$$





Relational Data Ring

- Set of relations over $\mathcal R$ with \uplus and \otimes forms a ring of relations
 - Relation ${f 0}$ maps every tuple to ${f 0} \in {\cal R}$
 - Relation ${\bf 1}$ maps the empty tuple to ${\bf 1}\in {\cal R}$, others to ${\bf 0}\in {\cal R}$
- Payloads: Relations over $\mathcal{R} = \mathbb{Z}$ with the same schema!

Α	В	\rightarrow	R[A, B]
a_1	b_1	\rightarrow	$egin{array}{c} C \\ \hline c_1 \to 1 \\ c_2 \to 1 \\ \hline \end{array}$
a ₂	b_1	\rightarrow	$\frac{\mid C \mid}{\mid c_3 \to 1}$

Keep results of conjunctive queries in payloads

Evaluating Conjunctive Queries using Relational Payloads

• Consider the conjunctive query:

$$Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)$$

• Compute Q using relations with relational payloads

$$Q = \bigoplus_{A} \bigoplus_{B} \bigoplus_{C} \bigoplus_{D} \bigoplus_{E} (R[A, B] \otimes S[A, C, E] \otimes T[C, D])$$

• Lifting (aggregate) functions:

$$g_X(x) = \left\{ egin{array}{c} |X \ \hline |x
ightarrow 1 \end{array}
ight. \quad ext{if X is a free variable} \ \hline \hline |()
ightarrow 1 \end{array}
ight. \quad ext{otherwise}$$

Listing Representation of Conjunctive Query Results

$$Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)$$

$\frac{\mathsf{A} \quad \mathsf{B} \quad \rightarrow \, \mathsf{R}[\mathsf{A},\mathsf{B}]}{\cdot}$

 a_1 $b_1
ightarrow \overline{()
ightarrow 1}$

 $a_1 \quad b_2 \rightarrow () \rightarrow 1$

 a_2 $b_3 \rightarrow () \rightarrow 1$ a_3 $b_4 \rightarrow () \rightarrow 1$

A C E \rightarrow S[A,C,E]

 a_1 c_1 $e_1 o \overline{)() o 1}$

 a_1 c_1 $e_2 \rightarrow () \rightarrow 1$

 a_1 c_2 $e_3 \rightarrow () \rightarrow 1$

 a_2 c_2 $e_4 \rightarrow () \rightarrow 1$

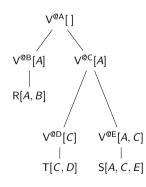
$C D \rightarrow T[C,D]$

 c_1 $d_1 \rightarrow () \rightarrow 1$

 c_2 $d_2 \rightarrow () \rightarrow 1$

 c_2 $d_3 \rightarrow () \rightarrow 1$

 c_3 $d_4 \rightarrow () \rightarrow 1$



Listing Representation of Conjunctive Query Results

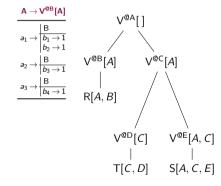
$$Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)$$

$\begin{array}{c|cccc} \underline{A} & \underline{B} & \rightarrow & \underline{R[A,B]} \\ \hline a_1 & b_1 & \rightarrow & () \rightarrow 1 \\ a_1 & b_2 & \rightarrow & () \rightarrow 1 \\ a_2 & b_3 & \rightarrow & () \rightarrow 1 \\ a_3 & b_4 & \rightarrow & () \rightarrow 1 \\ \end{array}$

 a_1 c_2 $e_3 \rightarrow |() \rightarrow 1$ a_2 c_2 $e_4 \rightarrow |() \rightarrow 1$

$\begin{array}{c|c} C & D \rightarrow T[C,D] \\ \hline c_1 & d_1 \rightarrow () \rightarrow 1 \\ c_2 & d_2 \rightarrow () \rightarrow 1 \\ c_2 & d_3 \rightarrow () \rightarrow 1 \end{array}$

 c_3 $d_4 \rightarrow () \rightarrow 1$



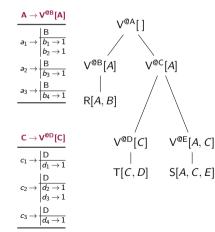
$$Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)$$

$\begin{array}{c|ccc} A & B \rightarrow R[A,B] \\ \hline a_1 & b_1 \rightarrow |() \rightarrow 1] \\ a_1 & b_2 \rightarrow |() \rightarrow 1] \\ a_2 & b_3 \rightarrow |() \rightarrow 1] \\ a_3 & b_4 \rightarrow |() \rightarrow 1] \end{array}$

$$c_2$$
 $d_2 \rightarrow \boxed{() \rightarrow 1}$
 c_2 $d_3 \rightarrow \boxed{() \rightarrow 1}$
 c_3 $d_4 \rightarrow \boxed{() \rightarrow 1}$

 $C D \rightarrow T[C,D]$

 $c_1 \quad d_1 \rightarrow () \rightarrow 1$



$$Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)$$

$A B \rightarrow R[A,B]$ $a_1 \quad b_1 \rightarrow () \rightarrow 1$ $a_1 \quad b_2 \rightarrow () \rightarrow 1$ $a_2 \quad b_3 \rightarrow () \rightarrow 1$ $a_3 b_4 \rightarrow () \rightarrow 1$

A C E \rightarrow S[A,C,E]

 $a_1 \quad c_1 \quad e_1 \rightarrow () \rightarrow 1$ a_1 c_1 $e_2 \rightarrow () \rightarrow 1$

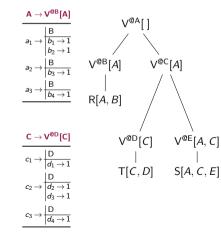
 a_1 c_2 $e_3 \rightarrow () \rightarrow 1$

 a_2 c_2 $e_4 \rightarrow () \rightarrow 1$

$C D \rightarrow T[C,D]$

 $c_1 \quad d_1 \rightarrow () \rightarrow 1$ c_2 $d_2 \rightarrow () \rightarrow 1$

 c_2 $d_3 \rightarrow () \rightarrow 1$ c_3 $d_4 \rightarrow () \rightarrow 1$



 $A C \rightarrow V^{0E}[A,C]$

 $a_1 c_1 \rightarrow () \rightarrow 2$

 $a_1 c_2 \rightarrow () \rightarrow 1$

 $a_2 c_2 \rightarrow () \rightarrow 1$

Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)

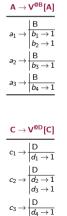
$A B \rightarrow R[A,B]$ $a_1 \quad b_1 \rightarrow () \rightarrow 1$ $a_1 \quad b_2 \rightarrow () \rightarrow 1$ $a_2 \quad b_3 \rightarrow () \rightarrow 1$ $a_3 b_4 \rightarrow () \rightarrow 1$

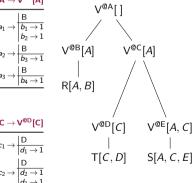
A C E \rightarrow S[A,C,E] $a_1 \quad c_1 \quad e_1 \rightarrow () \rightarrow 1$ a_1 c_1 $e_2 \rightarrow () \rightarrow 1$ $a_1 \quad c_2 \quad e_3 \rightarrow () \rightarrow 1$ a_2 c_2 $e_4 \rightarrow () \rightarrow 1$ $C D \rightarrow T[C,D]$ $c_1 \quad d_1 \rightarrow () \rightarrow 1$

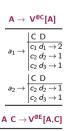
 c_2 $d_2 \rightarrow () \rightarrow 1$

 c_2 $d_3 \rightarrow () \rightarrow 1$

 c_3 $d_4 \rightarrow () \rightarrow 1$







 $a_1 c_1 \rightarrow () \rightarrow 2$

 $a_1 c_2 \rightarrow () \rightarrow 1$

 $a_2 c_2 \rightarrow () \rightarrow 1$

$$Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)$$

A B \rightarrow R[A,B]

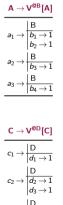
- $a_1 \quad b_1 \rightarrow () \rightarrow 1$
- $a_1 \quad b_2 \rightarrow () \rightarrow 1$ $a_2 \quad b_3 \rightarrow () \rightarrow 1$
- $a_3 b_4 \rightarrow () \rightarrow 1$

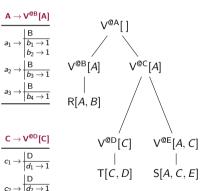
A C E \rightarrow S[A,C,E]

- $a_1 \quad c_1 \quad e_1 \rightarrow () \rightarrow 1$
- a_1 c_1 $e_2 \rightarrow () \rightarrow 1$
- $a_1 \quad c_2 \quad e_3 \rightarrow () \rightarrow 1$
- a_2 c_2 $e_4 \rightarrow () \rightarrow 1$

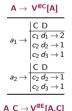
$C D \rightarrow T[C,D]$ $c_1 \quad d_1 \rightarrow () \rightarrow 1$

- c_2 $d_2 \rightarrow () \rightarrow 1$
- c_2 $d_3 \rightarrow () \rightarrow 1$
- c_3 $d_4 \rightarrow () \rightarrow 1$











Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)

$A B \rightarrow R[A,B]$

$$a_1$$
 $b_1 o \overline{)() o 1}$

$$a_1 \quad b_2 \rightarrow () \rightarrow 1$$

$$a_2 \quad b_3 \rightarrow () \rightarrow 1$$

$$a_3$$
 $b_4 \rightarrow () \rightarrow 1$

A C E \rightarrow S[A,C,E]

$$a_1$$
 c_1 $e_1 o \overline{)() o 1}$

$$a_1 \quad c_1 \quad e_2 \rightarrow () \rightarrow 1$$

$$a_1$$
 c_2 $e_3 \rightarrow () \rightarrow 1$

$$a_2$$
 c_2 $e_4 \rightarrow () \rightarrow 1$

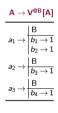
$C D \rightarrow T[C,D]$

$$c_1$$
 $d_1 o () o 1$

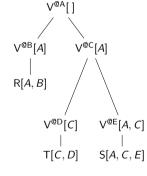
$$c_2$$
 $d_2 \rightarrow () \rightarrow 1$

$$c_2$$
 $d_3 \rightarrow () \rightarrow 1$

$$c_3$$
 $d_4 \rightarrow () \rightarrow 1$







Α	C	\rightarrow	V ^{@E} [A,C]
a ₁	c_1	\rightarrow	() → 2
a ₁	<i>c</i> ₂	\rightarrow	$() \rightarrow 1$
a 2	<i>c</i> ₂	\rightarrow	$() \rightarrow 1$

Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)

$A B \rightarrow R[A,B]$

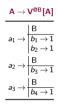
- a_1 $b_1 o () o 1$
- $a_1 \quad b_2 \rightarrow (0) \rightarrow 1$
- $a_2 \quad b_3 \rightarrow (1) \rightarrow 1$
- $a_3 b_4 \rightarrow () \rightarrow 1$

A C E \rightarrow S[A,C,E]

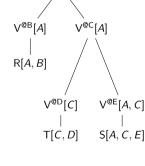
- a_1 c_1 $e_1 o \overline{)() o 1}$
- $a_1 \quad c_1 \quad e_2 \rightarrow () \rightarrow 1$
- a_1 c_2 $e_3 \rightarrow () \rightarrow 1$
- a_2 c_2 $e_4 \rightarrow () \rightarrow 1$

$C D \rightarrow T[C,D]$

- c_1 $d_1 o () o 1$
- c_2 $d_2 \rightarrow () \rightarrow 1$
- c_2 $d_3 \rightarrow () \rightarrow 1$
- c_3 $d_4 \rightarrow () \rightarrow 1$







$$A \rightarrow V^{0C}[A]$$

$$a_1 \rightarrow \begin{vmatrix} C \\ c_1 \rightarrow 2 \\ c_2 \rightarrow 2 \end{vmatrix}$$

$$a_2 \rightarrow \begin{vmatrix} C \\ c_2 \rightarrow 2 \end{vmatrix}$$

A $C \rightarrow$	V ^{@E} [A,C]
$a_1 c_1 \rightarrow$	
$a_1\;c_2\to$	$() \rightarrow 1$
$a_2 c_2 \rightarrow$	<u>() → 1</u>

Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)

$A B \rightarrow R[A,B]$

$$a_1$$
 $b_1 \rightarrow () \rightarrow 1$ a_1 $b_2 \rightarrow () \rightarrow 1$

$$a_2 \quad b_3 \rightarrow () \rightarrow 1$$

$$a_3 b_4 \rightarrow () \rightarrow 1$$

A C E \rightarrow S[A,C,E]

- $a_1 \quad c_1 \quad e_1 \rightarrow () \rightarrow 1$
- $a_1 \quad c_1 \quad e_2 \rightarrow () \rightarrow 1$
- $a_1 \quad c_2 \quad e_3 \rightarrow () \rightarrow 1$
- a_2 c_2 $e_4 \rightarrow () \rightarrow 1$

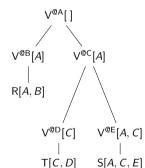
$C D \rightarrow T[C,D]$

- $c_1 \quad d_1 \rightarrow () \rightarrow 1$
- $c_2 d_2 \rightarrow () \rightarrow 1$
- c_2 $d_3 \rightarrow () \rightarrow 1$
- c_3 $d_4 \rightarrow () \rightarrow 1$









$$() \rightarrow V^{@A}[]$$

$$() \rightarrow A$$

$$() \rightarrow a_1 \rightarrow 8$$

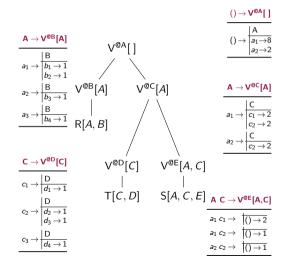
$$\begin{array}{c|c}
A \rightarrow V^{\text{OC}}[A] \\
\hline
a_1 \rightarrow \begin{vmatrix} C \\ c_1 \rightarrow 2 \\ c_2 \rightarrow 2 \end{vmatrix} \\
a_2 \rightarrow \begin{vmatrix} C \\ c_2 \rightarrow 2 \end{vmatrix}$$



Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)

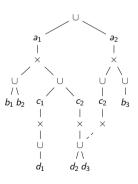
Constant Delay Enumeration

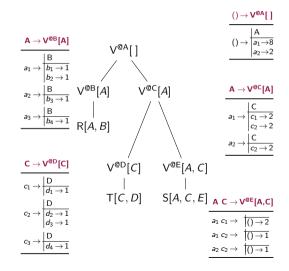
foreach a in V^{@A}
foreach b in V^{@B}
foreach c in V^{@C}
foreach d in V^{@D}
output (a,b,c,d)



Q(A, B, C, D) = R(A, B), S(A, C, E), T(C, D)

Factorized Join





Matrix Chain Multiplication

```
Input: Matrices \boldsymbol{A}_i of size of p_i \times p_{i+1} over some ring \mathcal{R} (i \in [n])
Compute: Product matrix \boldsymbol{A}[x_1, x_{n+1}] = \sum_{x_2 \in [p_2]} \cdots \sum_{x_n \in p_n} \prod_{i \in [n]} \boldsymbol{A}_i[x_i, x_{i+1}]
```

Modeled in F-IVM:

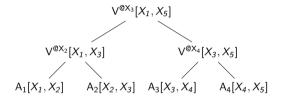
- Represent matrix $\mathbf{A}_i[x_i, x_{i+1}]$ by relation $A_i[X_i, X_{i+1}]$ with $A_i[a_i, a_{i+1}] = \mathbf{A}_i[a_i, a_{i+1}]$ (payloads are matrix entries)
- Express matrix multiplication by the query

$$A[X_1, X_{n+1}] = \bigoplus_{X_2} \cdots \bigoplus_{X_n} \bigotimes_{i \in [n]} A_i[X_i, X_{i+1}]$$

where each lifting function $g_{X_i}(X_j)$ maps any key to payload $\mathbf{1} \in \mathcal{R}$

Example: Product of Four Matrices

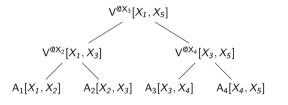
$$\mathsf{A}[X_1,X_5] = \bigoplus_{X_2} \bigoplus_{X_3} \bigoplus_{X_4} \bigotimes_{i \in [4]} \mathsf{A}_i[X_i,X_{i+1}] \text{ (each A_i encodes a $p \times p$ matrix)}$$



$$V^{@X_2} = \bigoplus_{X_2} A_1 \otimes A_2$$
 $V^{@X_4} = \bigoplus_{X_4} A_3 \otimes A_4$
 $V^{@X_3} = \bigoplus_{X_3} V^{@X_2} \otimes V^{@X_4}$
View computation time: $\mathcal{O}(p^3)$

Example: Product of Four Matrices

$$\mathsf{A}[X_1,X_5] = \bigoplus_{X_2} \bigoplus_{X_3} \bigoplus_{X_4} \bigotimes_{i \in [4]} \mathsf{A}_{\mathsf{i}}[X_i,X_{i+1}] \text{ (each A_i encodes a $p \times p$ matrix)}$$



$$V^{@X_2} = \bigoplus_{X_2} A_1 \otimes A_2$$
 $V^{@X_4} = \bigoplus_{X_4} A_3 \otimes A_4$
 $V^{@X_3} = \bigoplus_{X_3} V^{@X_2} \otimes V^{@X_4}$
View computation time: $\mathcal{O}(p^3)$

Propagation of
$$\delta A_2[X_2, X_3]$$
:

$$\begin{split} \delta \mathsf{V}^{@\mathsf{X}_2}[X_1,X_3] &= \bigoplus_{X_2} \delta \mathsf{A}_2[X_2,X_3] \otimes \mathsf{A}_2[X_2,X_3] \text{ (time } \mathcal{O}(p)) \\ \delta \mathsf{V}^{@\mathsf{X}_3}[X_1,X_5] &= \bigoplus_{X_3} \delta \mathsf{V}^{@\mathsf{X}_2}[X_1,X_3] \otimes \mathsf{V}^{@\mathsf{X}_4}[X_3,X_5] \text{ (time } \mathcal{O}(p^2)) \end{split}$$

Further propagation of delta requires $\mathcal{O}(p^3)$ time.

Example: Product of Four Matrices

$$\mathsf{A}[X_1,X_5] = \bigoplus_{X_2} \bigoplus_{X_3} \bigoplus_{X_4} \bigotimes_{i \in [4]} \mathsf{A}_i[X_i,X_{i+1}] \text{ (each A_i encodes a $p \times p$ matrix)}$$

$$V^{@X_3}[X_1, X_5]$$

$$V^{@X_4}[X_1, X_3]$$

$$A_1[X_1, X_2]$$

$$A_2[X_2, X_3]$$

$$A_3[X_3, X_4]$$

$$A_4[X_4, X_5]$$

$$V^{@X_2} = \bigoplus_{X_2} A_1 \otimes A_2$$
 $V^{@X_4} = \bigoplus_{X_4} A_3 \otimes A_4$
 $V^{@X_3} = \bigoplus_{X_3} V^{@X_2} \otimes V^{@X_4}$
View computation time: $\mathcal{O}(p^3)$

Propagation of a factorizable update
$$\delta A_2[X_2,X_3] = u[X_2] \otimes v[X_3]$$
:
$$\delta V^{@X_2}[X_1,X_3] = \underbrace{\left(\bigoplus_{X_2} A_1[X_1,X_2] \otimes u[X_2]\right)}_{u_2[X_1]} \otimes v[X_3] \text{ (time } \mathcal{O}(p^2))$$
$$\delta V^{@X_3}[X_1,X_5] = u_2[X_1] \otimes \left(\bigoplus_{X_2} v[X_3] \otimes V^{@X_4}[X_3,X_5]\right) \text{ (time } \mathcal{O}(p^2))$$

Summary: Factorized IVM

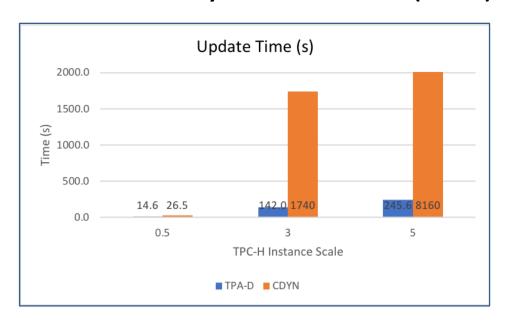
- Framework for unified IVM of in-database analytics
 - Captures many application scenarios via tasks-specific rings
- Based on 3 shades of factorization
 - Factorized query evaluation
 - Factorized representation of query results
 - Factorized updates
- Performance: Up to 2 OOM faster and 4 OOM less memory than state-of-the-art IVM techniques

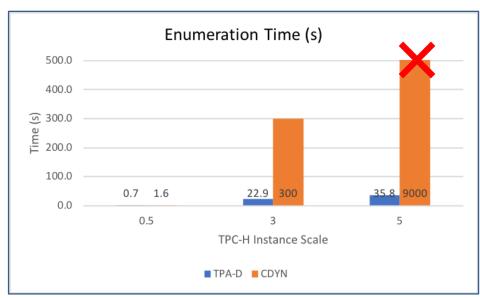
Outline

- Part I: Introduction
- Part II: Main Algorithmic Ideas in Dynamic Query Processing: Traditional IVM and Recent Advances
- Part III: Generalizations to Arbitrary Ring Structures
- Part IV: Dynamic Query Processing in Big Data Frameworks
 - Part V: Outlook

Are Centralized Algorithms Scalable?

Distributed Dynamic Yannakakis (TPA-D) vs Centralized Dynamic Yannakakis (CDYN)





Setup: 5 machines, 24GB RAM, 8 Cores / 16 Threads

0.5 = 2 million tuples; 3 = 20.5 million tuples; 5 = 34 million tuples

Why Distributed Streaming Frameworks?

- Efficiently process streams of big data
 - Data too big to fit into the memory of one machine
 - Centralized approaches are not efficient enough to process large data
- Add recovery to faults
 - Why? Distributed Computations + Messages
 - Failure
 Too expensive to start recomputing from the beginning

Distributed Streaming Frameworks











Trill







Main Objectives

• Supporting complex continuous queries



Low latency

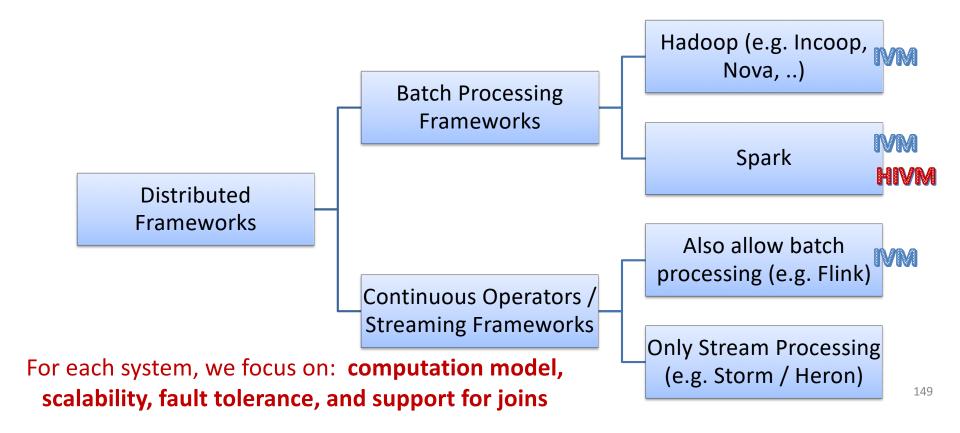
Scalability

Distributed streaming frameworks

Fault tolerance

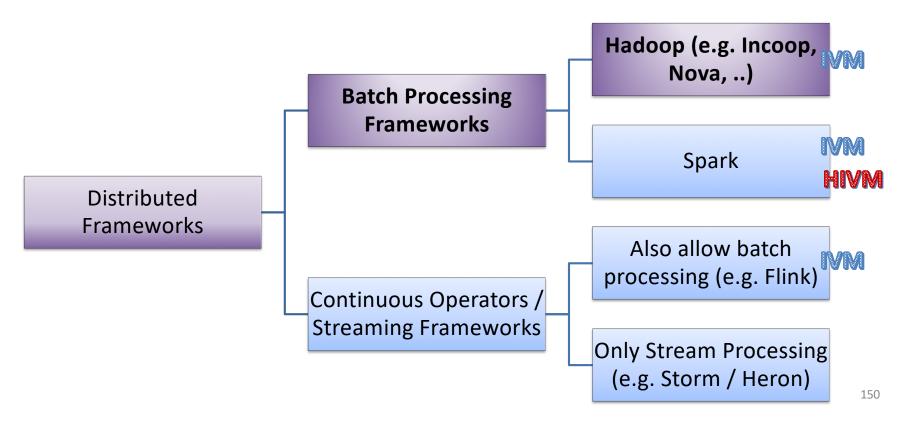
Categories of Frameworks Supporting Incremental Processing of Big Data

(Batch vs Stream Based Runtime Engine)



Categories of Frameworks Supporting Incremental Processing of Big Data

(Batch vs Stream Based Runtime Engine)



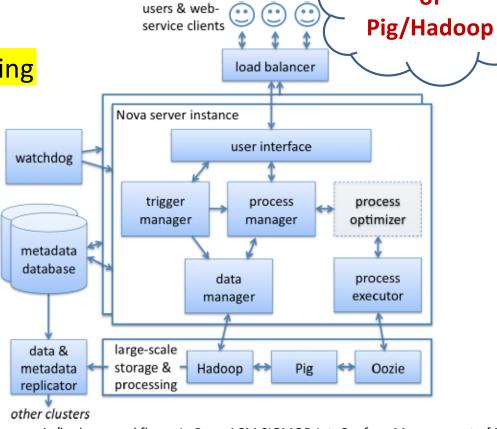
Nova [SIGMOD'11]

Goals:

IVM • Dynamic query processing

Scheduling

Optimizations



[SIGMOD'11] Christopher Olston et al. 2011. Nova: continuous pig/hadoop workflows. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 1081–1090.

Layer on top

Example Nova Workflow



Tasks



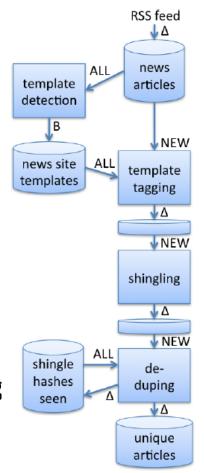
Channels / Data Containers

Data annotated with

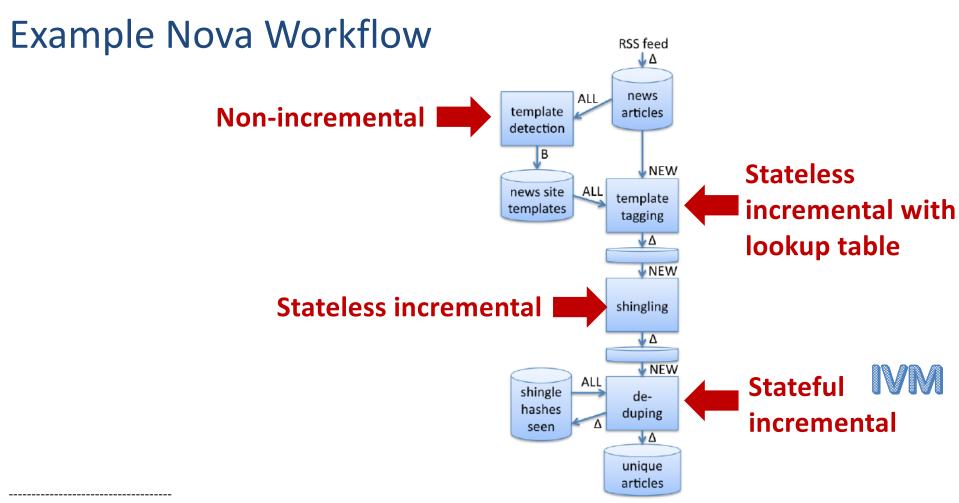
All Read complete snapshot

New Read NEW data

- B Emit full snapshot
- △ Emit new data that augment existing



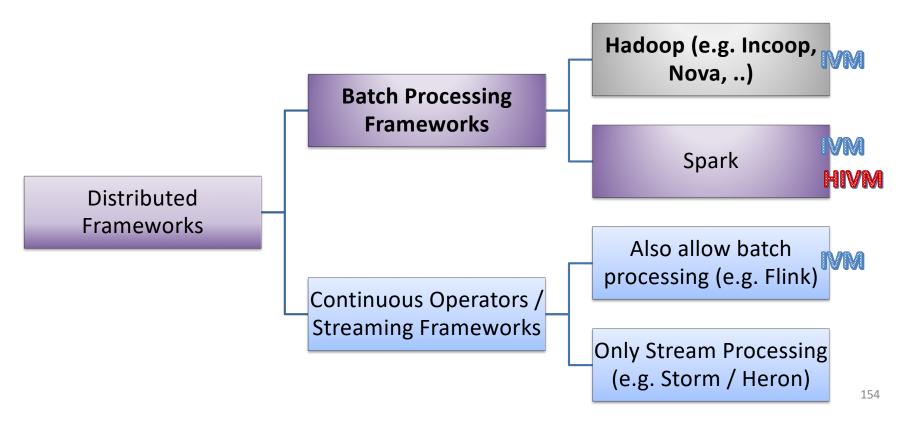
[SIGMOD'11] Christopher Olston et al. 2011. Nova: continuous pig/hadoop workflows. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 1081–1090.



[SIGMOD'11] Christopher Olston et al. 2011. Nova: continuous pig/hadoop workflows. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 1081–1090.

Categories of Frameworks Supporting Incremental Processing of Big Data

(Batch vs Stream Based Runtime Engine)





Spark Streaming [SOSP'13, SIGMOD'18]

Design objectives

- Process streams of large scale data
- Automatically handle faults and stragglers (parallel recovery)
- Integrate streaming with batch and interactive analysis



Credit: https://spark.apache.org/

[SOSP'13] Matei Zaharia, Tathagata Das, Haoyuan Li, Timothy Hunter, Scott Shenker, and Ion Stoica. 2013. Discretized Streams: Fault-tolerant Streaming Computation at Scale. In Proc. ACM Symp. on Operating Systems Principles (SOSP). 423–438.

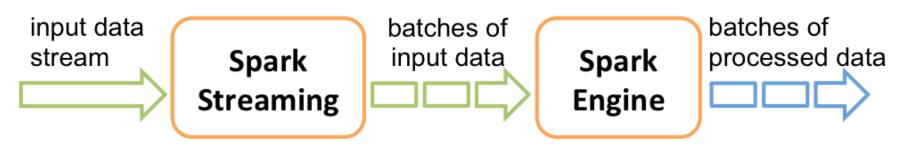
[SIGMOD'18] Michael Armbrust et al. 2018. Structured Streaming: A Declarative API for Real-Time Applications in Apache Spark. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 601–613.





D-streams:

- Computations => short, stateless, deterministic tasks
- Streamed data => fault-tolerant data structures (RDDs)
- Recomputed deterministically
- Spark engine for processing



Credit: https://spark.apache.org/

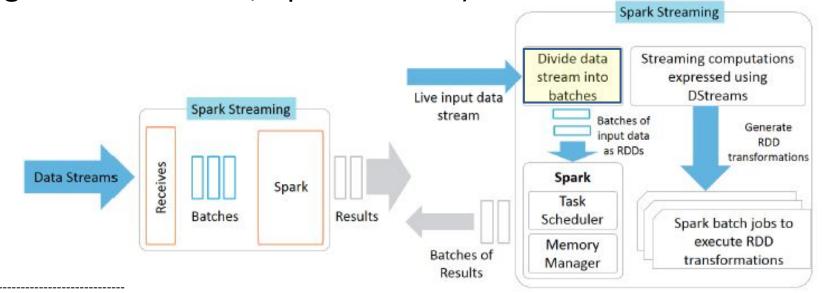


Spark Streaming – Computation Model

Input

Input should be re-playable

(e.g. Amazon Kenisis, Apache Kafka)



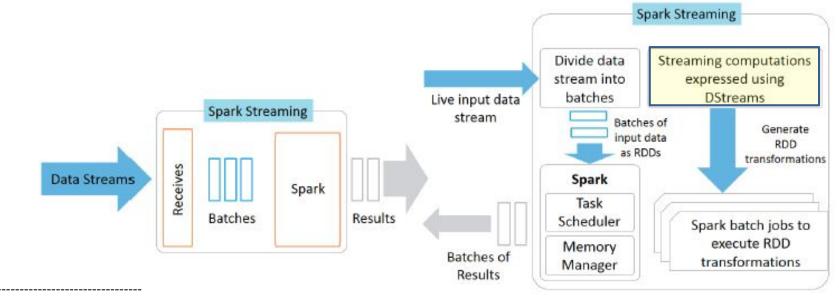
Credit: Michael Armbrust et al. 2018. Structured Streaming: A Declarative API for Real-Time Applications in Apache Spark. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 601–613.

Spark Streaming

Spark Streaming – Computation Model

Processing

 Time interval completes → spark streaming generate a parallel job (RDD transformation) to operate on the data



Credit: Michael Armbrust et al. 2018. Structured Streaming: A Declarative API for Real-Time Applications in Apache Spark. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 601–613.

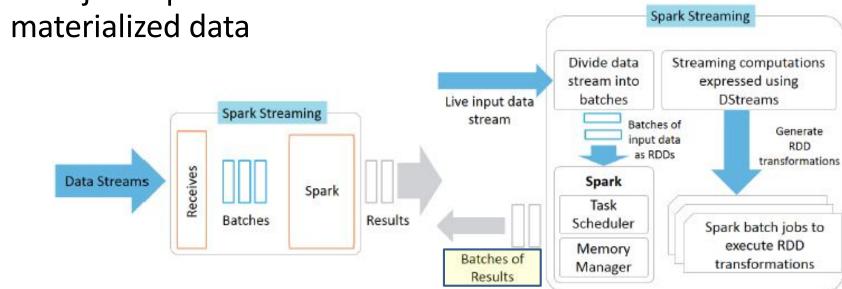


Spark Streaming – Computation Model

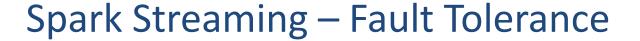
Output

Pushed to another system or stored as an RDD

Next jobs operate on: Streamed data + Intermediate

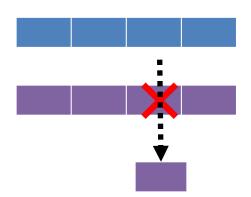


Credit: Michael Armbrust et al. 2018. Structured Streaming: A Declarative API for Real-Time Applications in Apache Spark. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 601–613.





- Parallel recovery
 - Streams and intermediate data are stored as RDDs
 - Frequent checkpointing
 - Failure => only missing partitions are recomputed
- Straggler mitigation
 - Run speculative copies of slow tasks
 - Deterministic computations + Idempotent sinks



Spark Streaming – Incremental Processing of Queries

Spark³ Streaming

- Stateless → fault tolerance
- Maintaining a State Arbitrary Stateful Operators

// Define an update function that simply tracks the

Spark³ Streaming

Spark Streaming – Support for Join Queries

- Allowed Joins:
 - Join between two data streams
 - Join between a data stream and a static dataset
- What about joining n datasets?
 - n-1 pair joins
 - Materialize intermediate join results
 - Dynamic query processing?

Running Example

Query from TPC-H Benchmark:

SELECT *

FROM lineitem L, supplier S, partsupp PS

WHERE L.suppkey = S.suppkey

and L.suppkey = PS.suppkey

and L.partkey = PS.partkey

[sk,pk]

[sk,pk]

[sk,pk]

[sk,pk]

[sk,pk]

Example: Spark Implementation



```
val dsL = spark
 .readStream
 .format( source = "kafka")
 .option("kafka.bootstrap.servers", "localhost:9093")
 .option("subscribe", "li-topic")
 .select( col = "value", cols = "timestamp")
 .as[(String,Timestamp)]
 .map(data => L(data._1, data._2))
 .withWatermark(_eventTime = "lTimestamp", delayThreshold = "10 seconds")
val dsPS Define datasets
                                                                    val tripleJoin =
 .format( source = "kafka")
 .option("kafka.bootstrap.servers", "localhost:9094")
                                                                       dsL
 .option="subscribe", "ps-topic")
                                                                          .join(dsPS,expr(expr = """lSK = psSK"""), joinType = "inner")
 .select( col = "value", cols = "timestamp")
                                                                          .join(dsS, expr( expr = """lSK = sSK"""), joinType = "inner")
 .withWatermark( eventTime = "psTimestamp", delayThreshold = "10 seconds"
val dsS = spark
 .readStream
 .format( source = "kafka")
 .option("kafka.bootstrap.servers", "localhost:9095")
```

Acknowledgment: Thanks to Omar Shahbaz Khan for preparing this code.

.withWatermark(eventTime = "sTimestamp", delayThreshold = "10 seconds")

.option("subscribe", "s-topic")

.map(data \Rightarrow S(data._1, data._2))

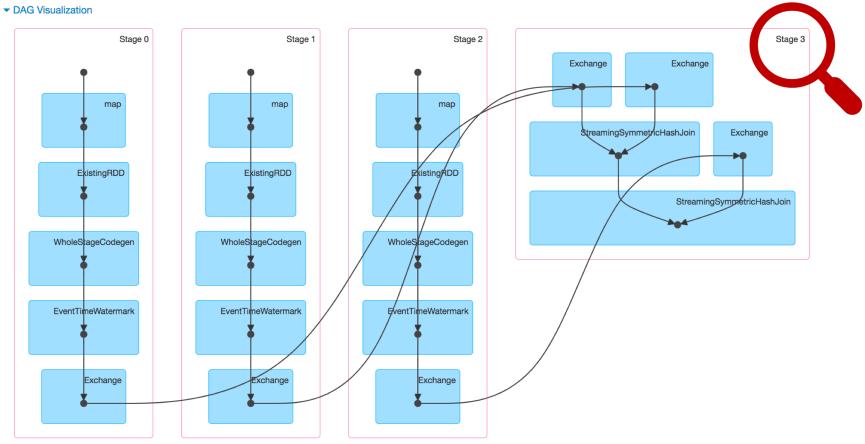
.as[(String,Timestamp)]

.select(col = "value", cols = "timestamp")

.load

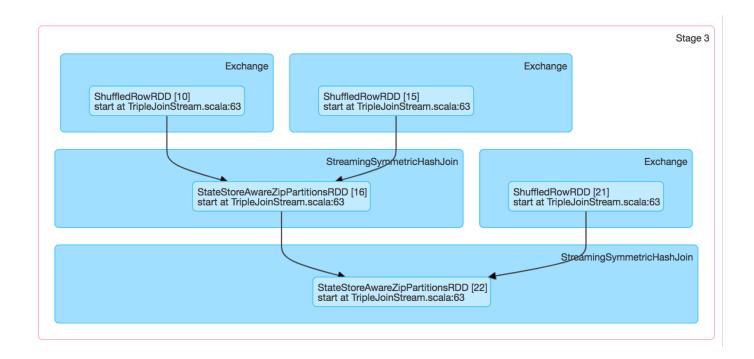
Example: Spark Execution Plan





Example: Spark Execution Plan







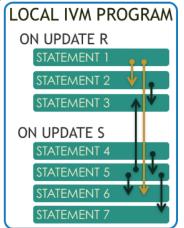
Distributed Higher-Order Incremental View Maintenance [SIGMOD'16]



HIVM + Spark Streaming

- On top of Spark: synchronous execution model
- Views local or distributed (partitioned)
- Parallel updates of views

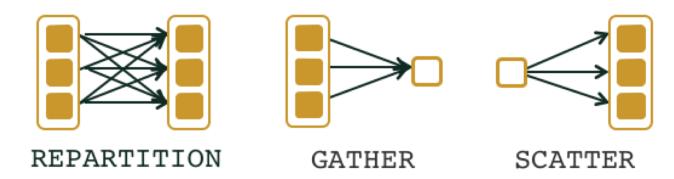
 dependency among programs
- Batching updates (well in some of the cases !)





Distributed HIVM Solution

- Annotate each node in the query plan with location tags
 - LOCAL, PARTITIONED BY KEY, RANDOM
- Insert communication operations into query plans: location transformers



Holistic optimization to minimize communication cost

[SIGMOD'16] Milos Nikolic, Mohammad Dashti, and Christoph Koch. 2015. How to Win a Hot Dog Eating Contest: Distributed Incremental View Maintenance with Batch Updates. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 511–526.

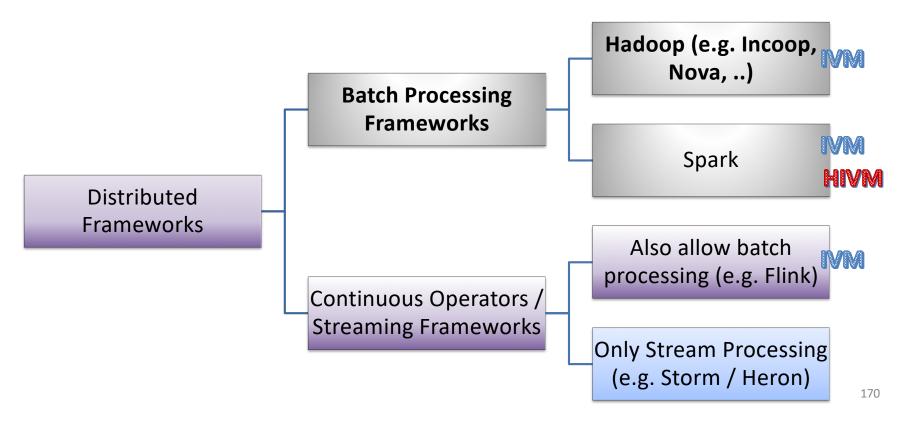




- Leverage Spark fault tolerance mechanism
- Periodic checkpointing in trigger program

Categories of Frameworks Supporting Incremental Processing of Big Data

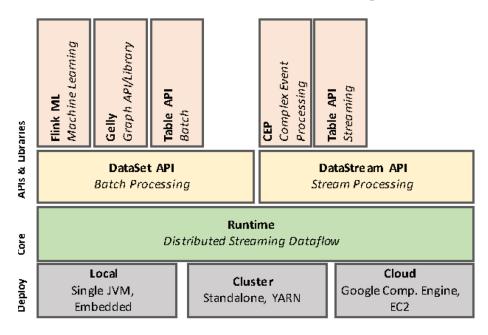
(Batch vs Stream Based Runtime Engine)



Flink [DE'15] (Based on Stratosphere[VLDBJ'14])



- No distinction between stream processing and batch processing
- However, core is a distributed streaming datflow engine



[DE'15] Carbone, Paris, et al. 2015. "Apache flink: Stream and batch processing in a single engine." *Bulletin of the IEEE Computer Society Technical Committee on Data Engineering* 36.4.

[VLDBJ'14] Alexander Alexandrov et al. 2014. The Stratosphere Platform for Big Data Analytics. The VLDB Journal 23, 6 (Dec. 2014), 939–964.





- Runtime program: DAG of stateful operators connected with data streams
 - Stateful operators: parallelized into one or more parallel instance (subtask)
 - Streams: partitioned into one or more stream partition (one per subtask)
- Static program →
 - finite stream
 - order of records is not important

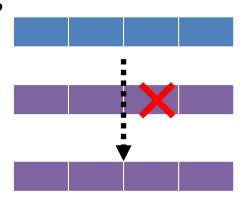
Flink – Fault Tolerance



- Consistency guarantee: exactly-once-processing
- Input data: persistent + re-playable
- Frequent checkpointing
 - Allow partial re-execution
 - Distributed consistent snapshots:



- Failure occurs →
 - Revert to latest snapshot
 - Redo the computation







- Join two streams
 - Window
 - Interval
- Join in Batch API allows custom join functions

Running Example

Query from TPC-H Benchmark:

SELECT *

FROM lineitem L, supplier S, partsupp PS

WHERE L.suppkey = S.suppkey

and L.suppkey = PS.suppkey

and L.partkey = PS.partkey

[sk,pk]

[sk,pk]

[sk,pk]

[sk,pk]

[sk,pk]



Example: Flink Implementation



```
val doubleJoinStream =
    lStream
    .join(psStream)
    .where(l => l.lSK)
    .equalTo(p => p.psSK)
    .window(TumblingEventTimeWindows.of(Time.seconds( seconds = 10)))
    .apply((l,p) => (l,p))

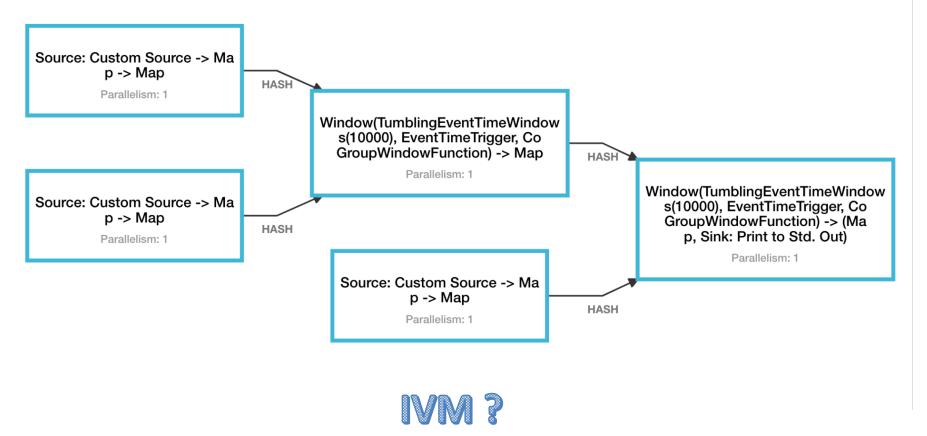
doubleJoinStream.map(j => j._1.toString + " | " + j._2.toString).print

val tripleJoinStream =
    doubleJoinStream
    .join(sStream)
    .where(_._1.lSK)
    .equalTo(_.sSK)
    .window(TumblingEventTimeWindows.of(Time.seconds( seconds = 10))).apply((j,s) => (j._1,j._2,s))
```

Acknowledgment: Thanks to Omar Shahbaz Khan for preparing this code.

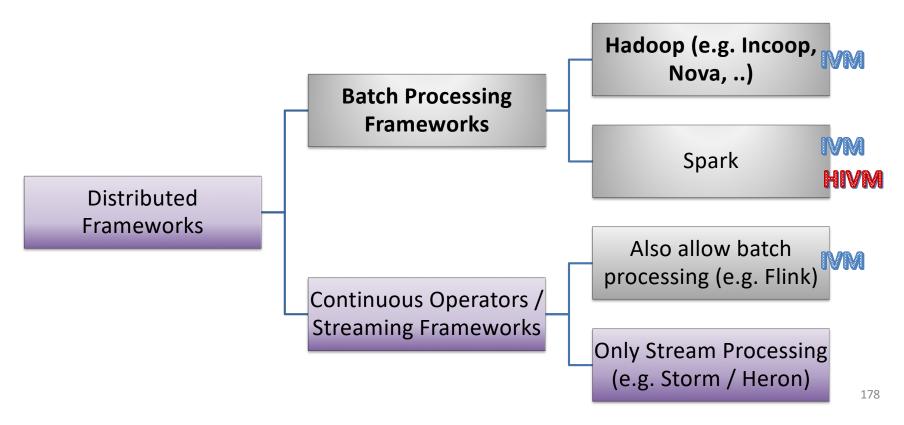
Example: Flink Execution Plan





Categories of Frameworks Supporting Incremental Processing of Big Data

(Batch vs Stream Based Runtime Engine)



Heron [SIGMOD'15, ICDE'17]



- Streaming engine
- Real-time performance for big data
- Based on + Same programming model of Storm [SIGMOD'14]

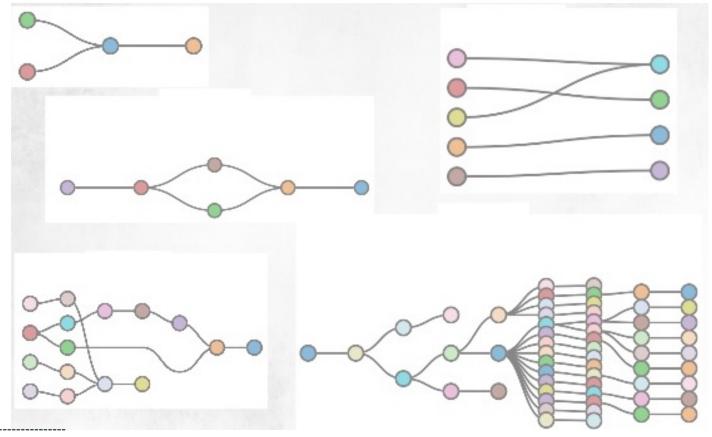
[SIGMOD'14] Ankit Toshniwal et al. 2014. Storm@Twitter. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 147–156. [SIGMOD'15] Sanjeev Kulkarni et al. 2015. Twitter Heron: Stream Processing at Scale. In Proc. ACM SIGMOD Int. Conf. on Management of Data. 239–250. [ICDE'17] Fu, Maosong et al. 2017. Twitter Heron: Towards Extensible Streaming Engines. In Proc. IEEE International Conference on Data Engineering (ICDE). 1165-1172.





- Queries are represented as topologies, which are directed acyclic graphs of spouts and bolts
 - Spout = tuple sources for the topology (e.g. pull data from kafka)
 - Bolt = process data and pass them to next bolt(s)
- Programmer specifies:
 - The number of tasks created for each spout and bolt (degree of parallelism)
 - Data partitioning

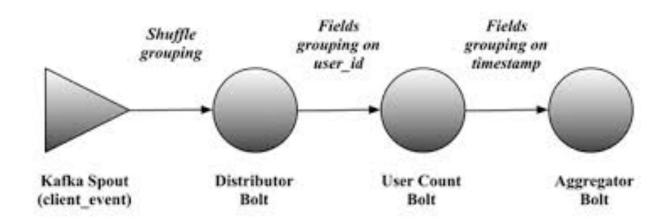
Heron Example Topologies



Credit: Real Time Analytics: Algorithms and Systems by Arun Kejariwal (https://apache.github.io/incubator-heron/docs/resources/)

(6)

Example Topology: Real Time Active Users



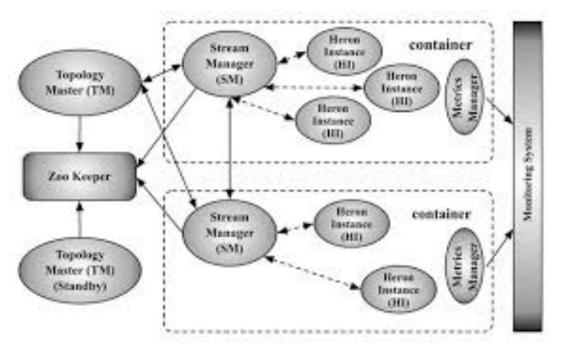
Credit: Fu, Maosong et al. 2017. Twitter Heron: Towards Extensible Streaming Engines. In Proc. *IEEE International Conference on Data Engineering (ICDE)*. 1165-1172.

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Heron Topology Architecture



- Topologies are submitted to a scheduler "Apache Aurora", which starts several containers:
 - Topology master
 - General container running:
 - Stream Manager,
 - Metric Manager, and
 - Heron Instances



Credit: Fu, Maosong et al. 2017. Twitter Heron: Towards Extensible Streaming Engines. In Proc. *IEEE International Conference on Data Engineering (ICDE)*. 1165-1172.

Heron – Fault Tolerance: Tuples Processing Semantics



- At most once:
 - No tuple is processed more than once
 - Some tuples might be dropped (Not processed by the topology)
- At least once:
 - Each tuple is processed at least once (multiple times happens)
 - Add new bolt "acker" to track the processing of each tuple
 - Developer custom code for state recovery

Heron – Fault Tolerance: Workers



- Topology Master
 - Metadata kept in Zookeeper
 - A standby version is created upon startup in case master fails
- Failure scenarios
 - Death of a Stream Manager or Heron Instances: restarted from within the container
 - Container failure or Machine failure:
 - A new container is started
 - Failure recovery procedure of Stream Manager and Heron Instances





- Storm SQL integration experimental feature → does not support joins or aggregations
- Heron Streamlet API (beta) → join operations of two streams
- Programmers write topology for applications
 - Advanced incremental view maintenance approach can be implemented as a topology ?

Running Example

Query from TPC-H Benchmark:

SELECT *

FROM lineitem L, supplier S, partsupp PS

WHERE L.suppkey = S.suppkey

and L.suppkey = PS.suppkey

and L.partkey = PS.partkey

[sk,pk]

[sk,pk]

[sk,pk]

[sk,pk]

[sk,pk]



Example: Heron/Storm Implementation

```
builder.setSpout( id = "li", lSpout, parallelism_hint = 1)
builder.setSpout( id = "ps", psSpout, parallelism_hint = 1)
                                                                                       Two step
builder.setSpout( id = "s", sSpout, parallelism_hint = 1)
                                                                                          ioin
val firstStepJoinBolt = new JoinBolt( sourceId = "li", fieldName = "lS key")
  .join( newStream = "ps", field = "psS_key", priorStream = "li")
  .select( commaSeparatedKeys = "lS key, l_obj, ps_obj")
  .withTumblingWindow(new Duration( value = 10, TimeUnit.SECONDS))
builder.setBolt( id = "firstStepJoin", firstStepJoinBolt, parallelism_hint = 1)
    .fieldsGrouping( componentId = "li", new Fields( fields = "lS key"))
    .fieldsGrouping( componentId = "ps", new Fields( fields = "psS_key"))
builder.setBolt( id = "liPsBolt", new DoubleJoinBolt).shuffleGrouping( componentId = "firstStepJoin")
val secondStepJoinBolt = new JoinBolt( sourceId = "liPsBolt", fieldName = "key")
  .join( newStream = "s", field = "s_key", priorStream = "liPsBolt")
  .select( commaSeparatedKeys = "key, l_obj, ps_obj, s_obj")
  .withTumblingWindow(new Duration( value = 10, TimeUnit.SECONDS))
builder.setBolt( id = "secondStepJoin", secondStepJoinBolt)
  .fieldsGrouping(componentId = "liPsBolt", new Fields(fields = "key"))
  .fieldsGrouping( componentId = "s", new Fields( fields = "s key"))
builder.setBolt( id = "liPsSBolt", new TripleJoinBolt).shuffleGrouping( componentId = "secondStepJoin")
```

Distributed Streaming Frameworks: Summary

	Spark Streaming	Flink	Storm/Heron
Input stream	Persistent +	Persistent +	No condition
Condition	Re-playable	Re-playable	
Input stream	D-Streams	Tuples	Tuples
Computation model	Stateless Tasks	Topology of Stateful Operations	Topology of Stateful bolts
Runtime Engine	Batch Processing	Stream Processing	Stream Processing
Support Batching	✓	✓	×
Fault tolerance	Exactly—once Parallel and partial Recovery	Exactly—once Parallel from Snapshot	At-most-once or At-least-once (programmer)

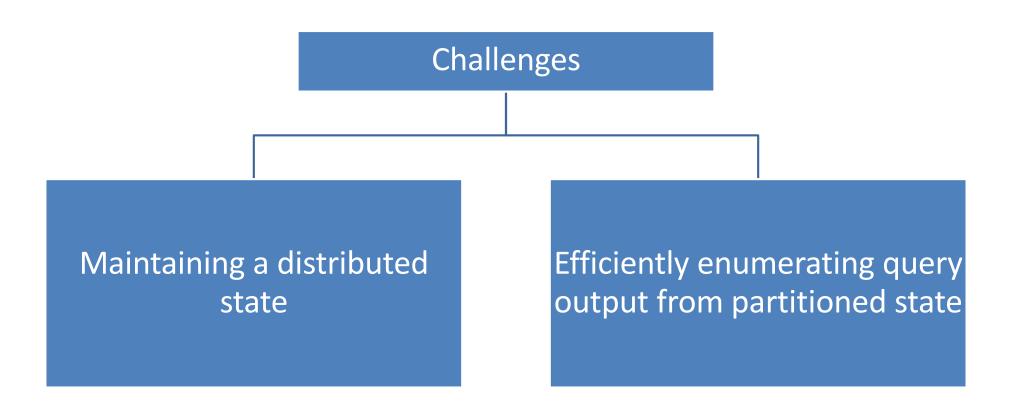
Outline

- Part I: Introduction
- Part II: Main Algorithmic Ideas in Dynamic Query Processing: Traditional IVM and Recent Advances
- Part III: Generalizations to Arbitrary Ring Structures
- Part IV: Dynamic Query Processing in Big Data Frameworks



Part V: Outlook

Parallel and Distributed Dynamic Query Processing



Challenge: Maintaining Distributed State

- Query state can be:
 - Materialized views (e.g. IVM, HIVM)
 - Custom query representation (e.g. Dynamic Yannakakis, F-IVM)
- Assumptions:
 - Stored in memory → otherwise, promised performance is not guaranteed
 - Optimized for small memory footprint
 - Processing on single core
 - Streamed tuples trigger updates to this state

However

- Frameworks such as Spark:
 - Agnostic to data content → shuffle data through network for join
 - Stateless operators

Therefore

- Distributed HIVM →
 custom partitioning + immutable RDDs periodically saved to HDFS
- Frameworks such as Storm:
 - Stateful operators
 - Implementing operators (bolts) that maintains intermediate state

Still Need to Address

- Reduce communication cost

 partitioning; co-locating data
- Fault tolerance
 - Lost messages between workers
 - Recomputing failed partitions

leverage existing frameworks; extra coding

Challenge: Enumerating Query Output from Partitioned State

- Consistency
 - Cause: simultaneous update to partitions of state maintain timestamps and track them
- Constant delay enumeration promised by Dynamic Yannakakis
 - Cannot be guaranteed: network messages to enumerate the output reduce messages between workers;
 - new model to describe enumeration that takes into account the communication cost

Conclusion

- For many applications, it is essential to analyze fast evolving big data in real time
- Many algorithmic ideas (single core):
 - Delta queries
 - Storing intermediate results
 - Dealing with Skews
- Generalizing to complex aggregates
- Distributed streaming frameworks → ill support of dynamic query processing
- New challenges: stateful operations yet scalable; consistency