A Conceptual Model of Temporal Data Warehouses and its Transformation to the ER and Object-Relational Models *

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1 Formalization of the MultiDim model

The following formalization is inspired from [2]. We first describe notations, assumptions, and meta-variables required for defining the abstract syntax and the semantics of the MultiDim model. Next, we give the abstract syntax of the model that allows the translation from the graphical representation to the equivalent textual representation. Finally, after describing the auxiliary functions, we define the semantics of the MultiDim model.

1.1 Notations

We use *SET*, *FSET*, and *TF* to denote the class of sets, the class of finite sets, and the class of total functions, respectively. Given $S_1, S_2, \ldots, S_n \in SET$, $S_i \oplus S_j$ indicates the disjoint union of sets, $S_i \cup S_j$ denotes the union of sets, and $S_1 \times S_2 \times \ldots \times S_n$ represents the Cartesian product over the sets S_1, S_2, \ldots, S_n . $\mathcal{P}(S)$ indicates powerset of the set S.

We write finite sets as $\{c_1, c_2, \ldots, c_n\}$, lists as $\langle c_1, c_2, \ldots, c_n \rangle$, and elements

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of Cartesian product as (c_1, c_2, \ldots, c_n) . For any set, we use \perp to denote the undefined value of the set.

1.2 Predefined data types

A data signature describes the predefined data types, operations, and predicates. The MultiDim model includes the basic data types *int*, *real*, and *string*; the inclusion of other data types is straightforward. These predefined data types as well as the operations and predicates on these have the usual semantics, and this interpretation is fixed, that is, defined once and for all.

The syntax of a data signature DS be given as follows:

- the sets DATA, OPNS, $PRED \in FSET$,
- a function $input \in TF$ such that $input : OPNS \to DATA^*$,
- a function $output \in TF$ such that $output : OPNS \rightarrow DATA$, and
- a function $args \in TF$ such that $args : PRED \to DATA^+$.

If $\sigma \in OPNS$, $input(\sigma) = \langle d_1, \ldots, d_n \rangle$ and $output(\sigma) = d$, this is denoted as $\sigma : \langle d_1, \ldots, d_n \rangle \to d$. If $\pi \in PRED$, with $args(\pi) = \langle d_1, \ldots, d_n \rangle$, this is denoted as $\pi : \langle d_1, \ldots, d_n \rangle$.

The predefined data types and some operators and predicates on them are as follows.

$$DATA \supseteq \{int, real, string\}$$

$$OPNS \supseteq \{+_i, -_i, *_i : int \times int \rightarrow int$$

$$+_r, -_r, *_r : real \times real \rightarrow real$$

$$/_i : int \times int \rightarrow real$$

$$/_r : real \times real \rightarrow real$$

$$cat : string \times string \rightarrow string$$

$$\dots \}$$

$$PRED \supseteq \{<_i, >_i, \leq_i, \geq_i, \neq_i : int \times int$$

$$<_r, >_r, \leq_r, \geq_r, \neq_r : real \times real$$

$$<_s, >_s, \leq_s, \geq_s, \neq_s : string \times string$$

$$\dots \}$$

 $S_D \in Schema_DECL$ – MultiDim schema declarations $D_D \in Dim_DECL$ – dimension declarations $L_D \in Lev_DECL$ – level declarations $CP_D \in CPRel_DECL$ – child-parent relationship declarations $F_D \in FactRel_DECL$ – fact relationship declarations $IC_D \in IC_DECL$ – integrity constraints declarations $H_D \in Hier_DECL$ – hierarchy declarations $A_D \in Att_DECL$ – attribute declarations $CP_S \in CP_SPEC$ – the set of child-parent specifications $I_S \in Inv_SPEC$ – the set of level involvement specifications $T_S \in Temp_SPEC$ – the set of specifications for temporal support $D \in Dimensions$ – the set of dimension names $F \in FactRels$ – the set of fact relationship names $L \in Levels$ – the set of level names $CP \in CPRels$ – the set of child-parent relationship names $H \in Hier$ – the set of hierarchy names $A \in Attributes$ – the set of attribute names $K \in 2^{Attributes}$ – the set of subsets of attribute names $d \in DATA$ – the set of basic data types supported by the MultiDim model $min, max \in Integer \ constants - the set of integer \ constants$ $temp \in \{LS, VT, TT, LT\}$ – the set of temporality types $t \in \{Time, Simple Time, Complex Time, Instant, InstantSet, Interval, \}$ *IntervalSet*} – the set of temporal data types $gr \in \{sec, min, hour, day, week, month, year\}$ – the set of granules

for temporality

1.4 Abstract syntax

1.5 Examples using the abstract syntax

In this section we show examples of the textual representation of a schema for temporal data warehouses. For brevity, only part of the textual representation is given.

The textual representation of the schema in Figure 1 is given next.

1.5.1 Level definitions

 ${\bf Level} \ Branch \ {\bf has}$

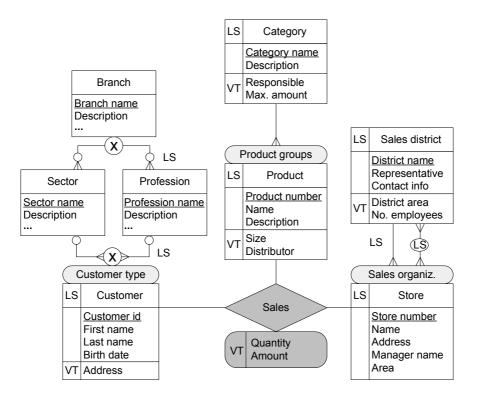


Fig. 1. Example of a schema including temporal and non-temporal elements.

Attribute Branch name of type string, Attribute Description of type string, . . .; Level Sector has Attribute Sector name of type string, Attribute Description of type string, . . .; Level Profession has Attribute Profession name of type string, Attribute Description of type string, . . .: Level Customer with temporality (LS, IntervalSet, month) has Attribute Customer id of type integer, Attribute First name of type string, Attribute *Last name* of type *string*, Attribute Birth date of type string, Attribute Address of type string with temporality (VT, IntervalSet, month), Level Product with temporality (LS, IntervalSet, month) has Attribute *Product number* of type *integer*, Attribute Name of type string, Attribute Description of type string, Attribute Size of type real

with temporality (VT, IntervalSet, month),
Attribute Distributor of type string

with temporality (VT, IntervalSet, month);

Level Store with temporality (LS, IntervalSet, year) has

Attribute Store number of type integer,
Attribute Name of type string,
Attribute Address of type string,
Attribute Manager name of type string,
Attribute Area of type string;

· · ·;

1.5.2 Child-parent relationship definitions

- C-P relationship SectBra involves Sector, Branch;
- C-P relationship *ProfBra* involves *Profession*, *Branch* with temporality (*LS*, *IntervalSet*, *month*);
- C-P relationship *CustSect* involves *Customer*, *Sector*;
- C-P relationship CustProf involves Customer, Profession with temporality (LS, IntervalSet, month);
- C-P relationship *ProdCat* involves *Product*, *Category*;
- C-P relationship *StoSD* involves *Store*, *Sales district* with temporality (*LS*, *IntervalSet*, *month*);

1.5.3 Dimension definitions

Dimension *Product* includes

hierarchy Product groups composed of ProdCat; Dimension Customer includes hierarchy Customer type composed of CustSect, CustProf, SectBra, ProfBra; Dimension Store includes

hierarchy Sales organiz. composed of StoSD;

1.5.4 Fact relationship definitions

Fact relationship Sales involves Customer, Product, Store;

\mathbf{has}

Attribute Quantity of type int with temporality (VT, instant, month), Attribute Amount of type real with temporality (VT, instant, month)

1.5.5 Constraint definitions

Customer id is primary key of Customer; Product number is primary key of Product; Store number is primary key of Store;

Snapshot participation of *Product* in *ProdCat* is (1,1); Lifespan participation of *Category* in *ProdCat* is (1,n); Snapshot participation of *Category* in *ProdCat* is (1,1); Lifespan participation of *Category* in *ProdCat* is (1,n);

Exclusive participation of *Customer* in *CustSect*, *CustProf*; **Exclusive participation of** *Branch* in *SectBra*, *ProfBra*;

1.6 Semantics

. . .

In this section we define the semantics of the textual representation of the MultiDim model. We begin by defining the semantics of the predefined data types, as well the model of time. Then, after presenting some auxiliary functions, we give the functions definining the semantics of the different components of the model.

1.6.1 Semantics of predefined data types

The semantics of the predefined data types is given by three functions

- A function $\mathcal{D}\llbracket DATA \rrbracket \in TF$ such that $\mathcal{D}\llbracket DATA \rrbracket : DATA \to SET$. We assume $\forall d \in DATA \ (\perp \in \mathcal{D}\llbracket DATA \rrbracket(d))$ where \perp represents an undefined value indicating an incorrect use of a function or an error.
- A function $\mathcal{D}[\![OPNS]\!] \in TF$ such that $\mathcal{D}[\![OPNS]\!] : OPNS \to TF$ and $\sigma : d_1 \times \ldots \times d_n \to d$ implies $\mathcal{D}[\![OPNS]\!](\sigma) : \mathcal{D}[\![DATA]\!](d_1) \times \ldots \times \mathcal{D}[\![DATA]\!](d_n) \to \mathcal{D}[\![DATA]\!](d) \in DATA$ for every $d \in DATA$.
- A function $\mathcal{D}[\![PRED]\!] \in TF$ such that $\mathcal{D}[\![PRED]\!] : PRED \to REL$ and $\pi : d_1 \times \ldots \times d_n \to d$ implies $\mathcal{D}[\![PRED]\!](\pi) \subseteq \mathcal{D}[\![DATA]\!](d_1) \times \ldots \times \mathcal{D}[\![DATA]\!](d_n) \to \mathcal{D}[\![DATA]\!](d) \in DATA$ for every $d \in DATA$.

For example, the semantics of the predefined data types and one of their operators are defined as follows:

 $\mathcal{D}\llbracket DATA \rrbracket(int) = \mathbb{Z} \cup \{\bot\} \\ \mathcal{D}\llbracket DATA \rrbracket(real) = \mathbb{R} \cup \{\bot\} \\ \mathcal{D}\llbracket DATA \rrbracket(string) = \mathbb{A}^* \cup \{\bot\}$

$$\mathcal{D}\llbracket +_i \rrbracket : \mathcal{D}\llbracket DATA \rrbracket(int) \times \mathcal{D}\llbracket DATA \rrbracket(int) \to \mathcal{D}\llbracket DATA \rrbracket(int) \\ = \begin{cases} i_1 \times i_2 \to i_1 + i_2 & \text{if } i_1, i_2 \in \mathbb{Z} \\ \bot & \text{otherwise} \end{cases}$$

1.6.2 The time model

We assume that the real time line is represented in the database by a baseline clock that is discrete and bounded on both ends [1–3]. The time domains are then ordered, finite sets of elements isomorphic to finite subsets of the integer numbers. The non-decomposable elements of the time domain are called *chronons*. Depending on application requirements consecutive chronons can be grouped into a larger unit called a *granule*, such as a second, a minute, or a day. *Granularity* represents the size of the granule, i.e., it is the time unit used for specifying the duration of the granule. We denote a granule as g. The granule g_{now} denotes the granule representing current time.

Following Gregersen and Jensen [2], we include a domain for each combination of the temporality types $temp \in \{LS, VT, TT, LT\}$ and granularities gr. These domains are denoted $D_{temp}^{gr} = \{g_1^{temp}, g_2^{temp}, \ldots, g_n^{temp}\}$, e.g., $D_{VT}^{month} = \{Jan, Feb, Mar, \ldots, Dec\}$. The domain of each temporal type is the union of domains represented by different granularities: $D_{temp} = \bigcup_{gr} (D_{temp}^{gr})$, e.g., for TT is $D_{TT} = \bigcup_{gr} (D_{TT}^{gr})$.

The real-world instants are represented by a granule according to the chosen granularity, e.g., a granule $g^{day} = 02/10/2006$ using a granularity day. A time interval is defined as the time between two instants called *begin* and *end* instants, i.e., $[g_{begin}, g_{end}]^{gr}$, e.g., $[25/09/2006, 02/10/2006]^{day}$. Thus, a time interval is a sequence of consecutive granules between the starting (g_{begin}) and ending (g_{end}) granules with granularity gr, e.g., all days between 25/09/2006and 02/10/2006. We also denote Int_{temp}^{gr} the interval for each temporality types, e.g., for VT it is Int_{VT}^{gr}

We also use set of instants and sets of intervals. An instant set over time domains is a finite union of instants, i.e., $IS^{gr} = g_1^{gr} \cup \ldots \cup g_n^{gr}$. We denote IS_{temp}^{gr} the instant set for each temporality type temp, i.e., for valid time, transaction time, lifespan, and loading time. Furthermore, an interval set, or a temporal element, over time domains is a finite union of intervals, i.e., $TE^{gr} = [g_{begin_1}, g_{end_1}]^{gr} \cup \ldots \cup [g_{begin_n}, g_{end_n}]^{gr}$. We denote $TE_{VT}^{gr}, TE_{TT}^{gr}, TE_{LS}^{gr}$ and TE_{LT}^{gr} as temporal elements of valid-time, transaction-time, lifespan, and loading time domains, respectively. Since our time domains are discrete and finite, we can define a temporal element as an element of the powerset $\mathcal{P}(D_{temp}^{gr})$.

1.6.3 Semantic domains

The MultiDim model includes the following value domains:

 $\begin{array}{l} D_S \cup \{\bot\} - \text{the set of surrogates} \\ D_S^L \subseteq D_S - \text{the set of surrogates assigned to } L \in Levels \\ D_S^{CP} \subseteq D_S - \text{the set of surrogates assigned to } CP \in CPRels \\ D_{LS} = \bigcup_{gr} (D_{LS}^{gr}) \cup \{\bot\} - \text{the lifespan domain} \\ D_{VT} = \bigcup_{gr} (D_{VT}^{gr}) \cup \{\bot\} - \text{the valid time domain} \\ D_{TT} = \bigcup_{gr} (D_{TT}^{gr}) \cup \{\bot\} - \text{the transaction time domain} \\ D_{LT} = \bigcup_{gr} (D_{LT}^{gr}) \cup \{\bot\} - \text{the data warehouse loading time domain} \\ \mathcal{D} \| DATA \| - \text{the set of basic domains} \end{array}$

1.6.4 Auxiliary functions

This section presents auxiliary functions required for defining the semantic functions.

Function attOf takes as argument a level declaration or an attribute declaration and returns the attribute names:

 $attOf(\textbf{Level } L \textbf{ has } A_D) = \\attOf(\textbf{Level } L \textbf{ with temporality } T_S \textbf{ has } A_D) = attOf(A_D) \\attOf(A_{D_1}, A_{D_2}) = attOf(A_{D_1}) \cup attOf(A_{D_2}) \\attOf(\textbf{Attribute } A \textbf{ is } A'_D) = A$

Function tempOf takes as argument a temporal specification and returns the temporality types of the specification, i.e., a subset of {LS, VT, TT, LT}:

 $tempOf(T_{S_1}, T_{S_2}) = tempOf(T_{S_1}) \cup tempOf(T_{S_2})$ $tempOf((temp, t, gr)) = \{temp\}$

Function *instants* takes as argument a temporal specification and returns a set of functions t (tuples). The domain of each function is the set of temporality types of the specification. The value domain of the temporality types is their underlying temporal domain. Intuitively, the function returns the set of instant tuples of a temporal specification.

 $instants(T_S) = \{t \mid t \in TF \land dom(t) = \{tempOf(T_S)\} \land \forall T_i \in tempOf(T_S)((T_i, t, gr) \in T_S \land t[T_i] \in D_{T_i}^{gr}\}$

Function *contains* takes as input an instant tuple c of a temporal specification and a set of instances of a child-parent relationship and returns the subset of the instances that contain c in its temporal support.

 $contains(c, \{t_1, \ldots, t_n\}) =$

$$\begin{cases} \emptyset & \text{if } n = 0\\ contains(c, \{t_1, \dots, t_{n-1}\}) \cup \{t_n\} & \text{if } \forall T_i \in dom(c)(c[T_i] \in t_n[T_i])\\ contains(c, \{t_1, \dots, t_{n-1}\}) & \text{otherwise} \end{cases}$$

Function cnt takes as input a level member m, a level L, and a set of instances of a child-parent relationship and returns the number of tuples in the childparent set in which the member m participates.

$$cnt(m, L, \{t_1, \dots, t_n\}) = \begin{cases} 0 & \text{if } n = 0\\ cnt(m, L, \{t_1, \dots, t_{n-1}\}) & \text{if } n \ge 1 \land t_n[s_L] \neq m\\ cnt(m, L, \{t_1, \dots, t_{n-1}\}) + 1 & \text{if } n \ge 1 \land t_n[s_L] = m \end{cases}$$

Function *lifespan* takes as input an identifier of a level member m and a level L, and returns the lifespan of the member, if any, or the empty set otherwise.

$$lifespan(m, L) = \begin{cases} t[LS] & \text{if } \exists t \in \mathcal{L}(L)(t[s] = m \land LS \in dom(t)) \\ \emptyset & \text{otherwise} \end{cases}$$

Predicate *inSch* takes as first argument a name of a level, of a child-parent relationship, or of a fact relationship, as well as a schema declaration. It returns true if the mentioned element is declared in the schema and *false* otherwise.

 $inSch(L, S_D) = inSch(L, D_D; L_D; CP_D; F_D; IC_D;) = inSch(L, L_D) = \begin{cases} true & \text{if Level } L \text{ has } A_D \in L_D \\ true & \text{if Level } L \text{ with temporality } T_S \text{ has } A_D \in L_D \\ false & \text{otherwise} \end{cases}$ $inSch(CP, S_D) = inSch(CP, D_D; L_D; CP_D; F_D; IC_D;) =$ $inSch(CP, CP_D) =$ $\begin{cases} true & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \in L_D \\ true & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{has distributing factor } \in L_D \\ true & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{with temporality } T_S \in L_D \\ true & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{with temporality } T_S \text{ has distributing factor } \in L_D \\ true & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{with temporality } T_S \text{ has distributing factor } \in L_D \end{cases}$ *false* otherwise $inSch(F, S_D) = inSch(F, D_D; L_D; CP_D; F_D; IC_D;) = inSch(F, F_D) =$ $\begin{cases} true & \text{if Fact relationship } F \text{ involves } I_S \in L_D \\ true & \text{if Fact relationship } F \text{ involves } I_S \text{ has } A_D \in L_D \\ false & \text{otherwise} \end{cases}$

Function *parOf* takes as argument the name of a child-parent relationship and returns the levels that participate in the relationship.

$$parOf(CP) = \begin{cases} parOf(\mathbf{C}-\mathbf{P} \text{ relationship } CP \dots) & \text{if } \mathbf{C}-\mathbf{P} \text{ relationship } CP \dots \in S_D \\ \bot & \text{otherwise} \\ parOf(\mathbf{C}-\mathbf{P} \text{ relationship } CP \text{ involves } I_S) = \\ parOf(\mathbf{C}-\mathbf{P} \text{ relationship } CP \text{ involves } I_S \text{ has } \dots) = \\ parOf(\mathbf{C}-\mathbf{P} \text{ relationship } CP \text{ involves } I_S \text{ with } \dots) = parOf(I_S) \\ parOf(I_{S_1}, I_{S_2}) = parOf(I_{S_1}) \cup parOf(I_{S_2}) \\ parOf(L) = \{L\} \end{cases}$$

Function *tempSpec* takes as argument the name of a child-parent relationship and returns the specification of its temporal support if the relationship is temporal and the empty set otherwise.

$$tempSpec(CP) = \begin{cases} \emptyset & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \in E_D \\ \emptyset & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{has distributing factor } \in E_D \\ T_S & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{with temporality } T_S \in E_D \\ T_S & \text{if C-P relationship } CP \text{ involves } L_1, L_2 \\ & \text{with temporality } T_S \text{ has distributing factor } \in E_D \\ \downarrow & \text{otherwise} \end{cases}$$

Recall that a level may participate several times in a fact relationship using different roles. The functions *role* and *level* takes an involvement of a level in a fact relationship and provides the role name or the level name, respectively.

 $\begin{aligned} & role(L) = L \\ & role(L \text{ as } role) = role \\ & level(L) = level(L \text{ as } role) = L \end{aligned}$

1.6.5 Semantic functions

We give next the signature and the definition of the semantic functions.

The semantic function \mathcal{I} determines the surrogate sets of the levels that are involved in a fact relationship or in a child-parent relationship.

$$\begin{aligned} \mathcal{I}\llbracket L \rrbracket : Levels \to D_S^L \\ \mathcal{I}\llbracket I_{S_1}, I_{S_2} \rrbracket = \mathcal{I}\llbracket I_{S_1} \rrbracket \times \mathcal{I}\llbracket I_{S_2} \rrbracket \\ \mathcal{I}\llbracket L \rrbracket = \mathcal{I}\llbracket L \text{ as } role \rrbracket = \begin{cases} D_S^L & \text{if } L \in Levels \\ \bot & \text{otherwise} \end{cases} \end{aligned}$$

The semantic function \mathcal{T} determines the time domains of the temporal support specified for a given level, child-parent relationship, or attribute.

 $\begin{aligned} \mathcal{T} &: Temp_SPEC \to D_{VT} \cup D_{TT} \cup D_{LS} \cup D_{LT} \\ \mathcal{T}\llbracket \text{with temporality } T_{S_1}, T_{S_2} \rrbracket = \mathcal{T}\llbracket T_{S_1} \rrbracket \times \mathcal{T}\llbracket T_{S_2} \rrbracket \\ \mathcal{T}\llbracket (temp, instant, gr) \rrbracket = D_{temp}^{gr} \\ \mathcal{T}\llbracket (temp, instantSet, gr) \rrbracket = \mathcal{P}(D_{temp}^{gr}) \\ \mathcal{T}\llbracket (temp, interval, gr) \rrbracket = (Int_{temp}^{gr}) \\ \mathcal{T}\llbracket (temp, intervalSet, gr) \rrbracket = \mathcal{P}(Int_{temp}^{gr}) \end{aligned}$

The semantic function \mathcal{A} defines the value domains of attribute declarations. If the attribute is of a predefined data type, then the value domain is that of the specified data type. If the attribute of type includes temporal support, this indicates that the value of this attribute changes over time. Therefore, the value domain of this attribute is a function from a time domain to a value domain.

$$\begin{aligned} \mathcal{A} : Attributes \times DATA \times Temp_SPEC \to \\ \mathcal{D}\llbracket DATA \rrbracket \cup (\mathcal{T}\llbracket T_S \rrbracket \to \mathcal{D}\llbracket DATA \rrbracket) \\ \mathcal{A}\llbracket A_{D_1}, A_{D_2} \rrbracket = \mathcal{A}\llbracket A_{D_1} \rrbracket \times \mathcal{A}\llbracket A_{D_2} \rrbracket \\ \mathcal{A}\llbracket A \texttt{tribute} \ A \ \texttt{of} \ A'_D \rrbracket = \mathcal{A}\llbracket A'_D \rrbracket \\ \mathcal{A}\llbracket \texttt{type} \ d \rrbracket = \begin{cases} \mathcal{D}\llbracket DATA \rrbracket (d) & \text{if} \ d \in DATA \\ \bot & \text{otherwise} \end{cases} \\ \mathcal{A}\llbracket \texttt{type} \ d \texttt{with temporality} \ T_S \rrbracket = \\ \begin{cases} \mathcal{T}\llbracket T_S \rrbracket \to \mathcal{D}\llbracket DATA \rrbracket (d) & \text{if} \ d \in DATA \land \Lambda T_S \in Temp_SPEC \\ \bot & \text{otherwise} \end{cases} \end{aligned}$$

The function \mathcal{S} defines the semantics of a MultiDim schema composed of definitions of levels, child-parent relationships, fact relationships, and integrity constraints. It defines each component of the underlying database and predicates that ensure validity and consistency of the database.

$$\begin{split} \mathcal{S} &: S_D \to \mathcal{S}[\![S_D]\!]\\ \mathcal{S}[\![S_D]\!] &= \mathcal{S}[\![L_D; CP_D; F_D; IC_D]\!]\\ \mathcal{S}[\![L_D; CP_D; F_D; IC_D]\!] &= \mathcal{L}[\![L_D]\!] \uplus \mathcal{CP}[\![CP_D]\!] \uplus \mathcal{F}[\![F_D]\!] \uplus \mathcal{IC}[\![IC_D]\!] \end{split}$$

The function \mathcal{L} defines the semantics of levels. The attributes of a level have an associated value domain. The association between a set of attributes $A = \{A_1, A_2, \ldots, A_n\}$ and the set of value domains D is given by a function $dom : A \to D$. A member of a level with its attributes can be seen as a tuple. A tuple t over a set of attributes A is actually a function that associates each attribute $A_i \in A$ with a value from the value domain $dom(A_i)$. For an attribute A we denote this value t[A].

The semantics of a level is thus a set of functions t (tuples). The domain of each function t is the surrogate attribute s and the set of attribute names belonging to the level L. The value domain of the surrogate attribute s is the set D_S^L of surrogate values assigned to the level L while the value domain of the attributes of the level L is determined by the semantics of the attribute declarations.

If the level has temporal support, this means that the database keeps lifespan, transaction time, and/or loading time for the members of the level. Recall that lifespan indicates the time during which the corresponding real-world member exists, transaction time refers to the time during which the member was current in the database, and loading time refers to the time when a member was introduced in the data warehouse. Therefore, the timestamps recording these temporality types must be associated with the member.

The function \mathcal{L} applied to a composition of level definitions returns the disjoint union of the functions applied to each component. This is because each level defines a unique set of tuples, which is stored separately in the database.

$$\begin{split} \mathcal{L} : Levels \times Temp_SPEC \times Att_DECL \to \mathcal{I}\llbracket L \rrbracket \times \mathcal{A}\llbracket A_D \rrbracket \cup \\ \mathcal{I}\llbracket L \rrbracket \times \mathcal{T}\llbracket T_S \rrbracket \times \mathcal{A}\llbracket A_D \rrbracket \\ \mathcal{L}\llbracket L_{D_1}; L_{D_2} \rrbracket = \mathcal{L}\llbracket L_{D_1} \rrbracket \uplus \mathcal{L}\llbracket L_{D_2} \rrbracket \\ \mathcal{L}\llbracket Level \ L \ has \ A_D \rrbracket = \\ \{t \mid t \in TF \land dom(t) = \{s, attOf(A_D)\} \land t[s] \in D_S^L \land \\ \forall A_i \in attOf(A_D) \ (t[A_i] \in \mathcal{A}\llbracket \mathbf{Attribute} \ A_i \ \mathbf{of} \ A'_D \rrbracket) \} \\ \mathcal{L}\llbracket Level \ L \ with \ temporality \ T_S \ has \ A_D \rrbracket = \\ \{t \mid t \in TF \land dom(t) = \{s, tempOf(T_S), attOf(A_D)\} \land t[s] \in D_S^L \land \\ \forall T_i \in tempOf(T_S)(t[T_i] \in \mathcal{T}\llbracket (T_i, t, gr) \rrbracket) \land \\ \forall A_i \in attOf(A_D)(t[A_i] \in \mathcal{A}\llbracket \mathbf{Attribute} \ A_i \ \mathbf{of} \ A'_D \rrbracket) \} \end{split}$$

The function \mathcal{CP} define the semantics of child-parent relationships. A childparent relationship relates a child and a parent level and may have in addition temporal support and/or a distributing factor. Their semantics is thus a set of tuples t relating a child and a parent member. Members are identified through their surrogates with the value domain defined by \mathcal{I} . If the relationship includes a distributing factor, the domain of the function t includes additionally an attribute d; its value domain is the set of real numbers. If the relationship includes temporal support, the timestamps for the different temporality types must be kept.

Since each child-parent relationship defines a unique set of tuples, if the function CP is applied to a composition of child-relationship relationship definitions, it returns the disjoint union of the functions applied to each component.

$$\begin{split} \mathcal{CP} &: CPRels \times Inv_SPEC \times Temp_SPEC \times Attributes \rightarrow \\ \mathcal{I}\llbracket I_S \rrbracket \cup \mathcal{I}\llbracket I_S \rrbracket \times \mathcal{D}\llbracket DATA \rrbracket \cup \mathcal{I}\llbracket I_S \rrbracket \times \mathcal{T}\llbracket T_S \rrbracket \cup \\ \mathcal{I}\llbracket I_S \rrbracket \times \mathcal{T}\llbracket T_S \rrbracket \times \mathcal{D}\llbracket DATA \rrbracket \\ \mathcal{CP}\llbracket CP_{D_1}; CP_{D_2} \rrbracket = \mathcal{CP}\llbracket CP_{D_1} \rrbracket \uplus \mathcal{CP}\llbracket CP_{D_2} \rrbracket \\ \mathcal{CP}\llbracket C\mathbf{P} \mathbf{relationship} \ CP \ \mathbf{involves} \ L_1, L_2 \rrbracket = \\ \{t \mid t \in TF \land dom(t) = \{s_{L_1}, s_{L_2}\} \land \\ t[s_{L_1}] \in \mathcal{I}\llbracket L_1 \rrbracket \land t[s_{L_2}] \in \mathcal{I}\llbracket L_2 \rrbracket \} \end{split}$$

 $\mathcal{CP}\llbracket \mathbf{C}-\mathbf{P} \text{ relationship } CP \text{ involves } L_1, L_2 \\ \text{has distributing factor} \rrbracket = \\ \{t \mid t \in TF \land dom(t) = \{s_{L_1}, s_{L_2}, d\} \land \\ t[s_{L_1}] \in \mathcal{I}\llbracket L_1 \rrbracket \land t[s_{L_2}] \in \mathcal{I}\llbracket L_2 \rrbracket \land t[d] \in \mathcal{D}\llbracket DATA \rrbracket (real) \} \\ \mathcal{CP}\llbracket \mathbf{C}-\mathbf{P} \text{ relationship } CP \text{ involves } L_1, L_2 \text{ with temporality } T_S \rrbracket = \\ \{t \mid t \in TF \land dom(t) = \{s_{L_1}, s_{L_2}, tempOf(T_S)\} \land t[s_{L_1}] \in \mathcal{I}\llbracket L_1 \rrbracket \land \\ t[s_{L_2}] \in \mathcal{I}\llbracket L_2 \rrbracket \land \forall T_i \in tempOf(T_S)(t[T_i] \in \mathcal{T}\llbracket (T_i, t, gr) \rrbracket) \land \\ (LS \in tempOf(T_S) \Rightarrow t[LS] \subseteq lifespan(s_{L_1}, L_1) \cap lifespan(s_{L_2}, L_2)) \} \\ \mathcal{CP}\llbracket \mathbf{C}-\mathbf{P} \text{ relationship } CP \text{ involves } L_1, L_2 \text{ with temporality } T_S \\ \text{ has distributing factor} \rrbracket = \\ \{t \mid t \in TF \land dom(t) = \{s_{L_1}, s_{L_2}, tempOf(T_S), d\} \land t[s_{L_1}] \in \mathcal{I}\llbracket L_1 \rrbracket \land \\ t[s_{L_2}] \in \mathcal{I}\llbracket L_2 \rrbracket \land \forall T_i \in tempOf(T_S)(t[T_i] \in \mathcal{T}\llbracket (T_i, t, gr) \rrbracket) \land \\ (LS \in tempOf(T_S) \Rightarrow t[LS] \subseteq lifespan(s_{L_1}, L_1) \cap lifespan(s_{L_2}, L_2)) \land \\ t[s_{L_2}] \in \mathcal{I}\llbracket L_2 \rrbracket \land \forall T_i \in tempOf(T_S)(t[T_i] \in \mathcal{T}\llbracket (T_i, t, gr) \rrbracket) \land \\ (LS \in tempOf(T_S) \Rightarrow t[LS] \subseteq lifespan(s_{L_1}, L_1) \cap lifespan(s_{L_2}, L_2)) \land \\ t[d] \in \mathcal{D}\llbracket DATA \rrbracket (real) \} \end{aligned}$

Notice that the two last definitions above enforce the constraint that the lifespan of an instance of a temporal child-parent relationship must be included in the intersection of lifespans of its participating members.

The function \mathcal{F} defines the semantics of fact relationships. A fact relationship relates several levels and may have attributes. Its semantics is thus a set of tuples t defining a member from each of its levels, as well as values for its attributes. Recall that a level may participate several times in a fact relationship using different roles. If this is the case the role name is used instead of the level name in the domain of function t. Members are identified through their surrogates with the value domain defined by \mathcal{I} . If the fact relationship has attributes, the domain of the function t includes additionally the set of attribute names. The value domains of these attributes are determined by the semantics of the attribute declarations. As for the level and the child-parent relationships, a fact relationship defines a unique set of tuples that are stored separately in the database.

$$\begin{aligned} \mathcal{F} : FactRels \times Inv_SPEC \times Att_DECL \to \mathcal{I}\llbracket I_S \rrbracket \cup \mathcal{I}\llbracket I_S \rrbracket \times \mathcal{A}\llbracket A_D \rrbracket \\ \mathcal{F}\llbracket F_{D_1}; F_{D_2} \rrbracket = \mathcal{F}\llbracket F_{D_1} \rrbracket \uplus \mathcal{F}\llbracket F_{D_2} \rrbracket \\ \mathcal{F}\llbracket \textbf{Fact relationship } F \textbf{ involves } I_S \rrbracket = \\ & \{t \mid t \in TF \land dom(t) = \{\bigcup_{L_i \in I_S} s_{role(L_i)}\} \land \\ \forall L_i \in I_S (t[s_{role(L_i)}] \in \mathcal{I}\llbracket level(L_i) \rrbracket)\} \\ \mathcal{F}\llbracket \textbf{Fact relationship } F \textbf{ involves } I_S \textbf{ has } A_D \rrbracket = \\ & \{t \mid t \in TF \land dom(t) = \{\bigcup_{L_i \in I_S} s_{role(L_i)}, attOf(A_D)\} \land \\ \forall A_i \in attOf(A_D) (t[A_i] \in \mathcal{A}\llbracket \textbf{Attribute } A \textbf{ of } A'_D \rrbracket) \land \\ \forall L_i \in I_S (t[s_{role(L_i)}] \in \mathcal{I}\llbracket level(L_i) \rrbracket) \} \end{aligned}$$

The function \mathcal{IC} defines the semantics of the integrity constraints. The semantics of a constraint is a set of predicates that the database must satisfy. In the textual representation all constraints are separate constructs, so the predicates must first verify that the constructs (e.g, levels, relationships) mentioned in the constraints belongs to the schema using the function inSch.

$$\mathcal{IC}: IC_D \to PRED \\ \mathcal{IC}\llbracket IC_{D_1}; IC_{D_2} \rrbracket = \mathcal{IC}\llbracket IC_{D_1} \rrbracket \wedge \mathcal{IC}\llbracket IC_{D_2} \rrbracket$$

The primary key constraint ensures that the values of the key attributes are unique for all members of the level.

 $\begin{aligned} \mathcal{IC}\llbracket K \text{ is primary key of } L\rrbracket &= inSch(L, S_D) \land \\ ((K \subseteq attOf(\textbf{Level } L \textbf{ has } A_D) \land \forall t_i, t_j \in \mathcal{L}\llbracket \textbf{Level } L \textbf{ has } A_D \rrbracket \\ (t_i[K] = t_j[K] \Rightarrow t_i[s] = t_j[s])) \lor \\ (K \subseteq attOf(\textbf{Level } L \textbf{ with temporality } T_S \textbf{ has } A_D) \land \\ \forall t_i, t_j \in \mathcal{L}\llbracket \textbf{Level } L \textbf{ with temporality } T_S \textbf{ has } A_D \rrbracket \land \\ (T\llbracket T_S \rrbracket \to t_i[K] = \mathcal{T}\llbracket T_S \rrbracket \to t_j[K] \Rightarrow T\llbracket T_S \rrbracket \to t_i[s] = \mathcal{T}\llbracket T_S \rrbracket \to t_j[s])) \end{aligned}$

The cardinality constraints ensure that a child member can be related to minimum *min* and maximum *max* parent members. Three cases must be considered: usual cardinality constraints for non-temporal relationships as well as snapshot and lifespan cardinality constraints for temporal relationships. In the case of usual cardinality constraints, for every member m of the level L we use the function *cnt* to determine the number of tuples belonging to the semantics of the child-parent relationship in which m participates. Snapshot cardinality constraints must be satisfied at each instant tuple c of the temporal domain of the relationship. Therefore, we use the function *contains* to obtain the subset of the tuples belonging to the semantics of the child-parent relationship that contains the instant tuple c. Then the function cnt is applied to this subset. In addition, if the level participating in the relationship is temporal, then for each instant belonging to the lifespan of a member m, it must be related to a valid member of the other level through an instance of the relationship. Finally, lifespan cardinality constraints must be satisfied during the whole temporal domain of the relationship.

$$\begin{split} \mathcal{IC}\llbracket \mathbf{Participation of } L \ \mathbf{in } CP \ \mathbf{is } (min, max) \rrbracket = \\ & inSch(L, S_D) \wedge inSch(CP, S_D) \wedge L \in parOf(CP) \wedge \forall m \in D_S^L \\ & (min \leq cnt(m, L, \mathcal{CP}\llbracket \mathbf{C-P \ relationship } CP \dots \rrbracket) \leq max) \\ \mathcal{IC}\llbracket \mathbf{Snapshot \ participation \ of } L \ \mathbf{in } CP \ \mathbf{is } (min, max) \rrbracket = \\ & inSch(L, S_D) \wedge inSch(CP, S_D) \wedge L \in parOf(CP) \wedge \\ & \forall c \in instants(tempSpec(CP)) \ \forall m \in D_S^L(min \leq \\ & cnt(m, L, contains(c, \mathcal{CP}\llbracket \mathbf{C-P \ relationship } CP \dots \rrbracket)) \leq max) \wedge \\ & \forall m \in D_S^L \ \forall c \in lifespan(m, L) \ \exists t \in \mathcal{CP}\llbracket \mathbf{C-P \ relationship } CP \dots \rrbracket) \\ & (t[s_L] = m \wedge c \in t[LS]) \\ \\ & \mathcal{IC}\llbracket \mathbf{Lifespan \ participation \ of } L \ \mathbf{in } CP \ \mathbf{is } (min, max) \rrbracket = \\ & inSch(L, S_D) \wedge inSch(CP, S_D) \wedge L \in parOf(CP) \wedge \forall m \in D_S^L \end{split}$$

 $(min \leq cnt(m, L, CP [[C-P relationship CP...]]) \leq max)$

A member of a level that participates exclusively in a set of child-parent relationships (i.e., a member of a splitting or joining level) cannot be involved in more than one of these relationships.

$$\mathcal{IC}[\![\mathbf{Exclusive participation of } L \text{ in } CP_S]\!] = inSch(L, S_D) \land \\ \forall CP_i \in CP_S(inSch(CP_i, S_D)) \land \neg (\exists CP_i, CP_j \in CP_S \\ \exists t_1 \in \mathcal{CP}[\![\mathbf{C}\text{-}\mathbf{P} \text{ relationship } CP_i \text{ involves } \dots]\!] \\ \exists t_2 \in \mathcal{CP}[\![\mathbf{C}\text{-}\mathbf{P} \text{ relationship } CP_j \text{ involves } \dots]\!] \\ (i \neq j \land t_1[s_L] = t_2[s_L]))$$

Notice that in the above formalization dimensions and hierarchies do not have semantic interpretations. However, they are needed for defining meaningful OLAP operations. Dimensions are required for the drill-across operation that allows to compare measures from different fact relationships. Hierarchies are needed for defining aggregations for the roll-up and drill-down operations. Such operations are beyond the scope of this paper.

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