

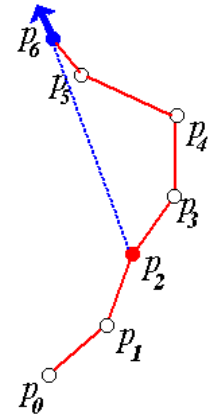
Multi-scale Windowing over Trajectory Streams

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GeoStreaming

- *Geospatial streams* derived from real-time data acquisition
 - geosensors ~ *vector data* • imagery/satellite ~ *raster data* (mostly)
- Interest on monitoring *location-aware* moving objects:
 - *numerous* vehicles, people, merchandise, animals,...
 - **PRESENT** → record their current *location*
 - **PAST** → maintain historical *trajectories*
 - **FUTURE** → predict routes / estimate trends
- Streaming locations from GPS/RFID/GSM...
 - *timestamped, georeferenced points* pose challenges:
 - consume fluctuating, intermittent, voluminous positional updates
 - provide timely response to spatiotemporal *Continuous Queries (CQ)*
 - overcome lack of suitable operators in traditional DBMS
 - Towards a new processing paradigm: *GeoStreaming*
 - query evaluation – in-memory indexing – data reduction/approximation



Windowing over Data Streams

- Continuous queries evaluated against stream “chunks”

- Infeasible to retain the entire stream “history”

- for online computation in *main memory*, not disk-bound storage

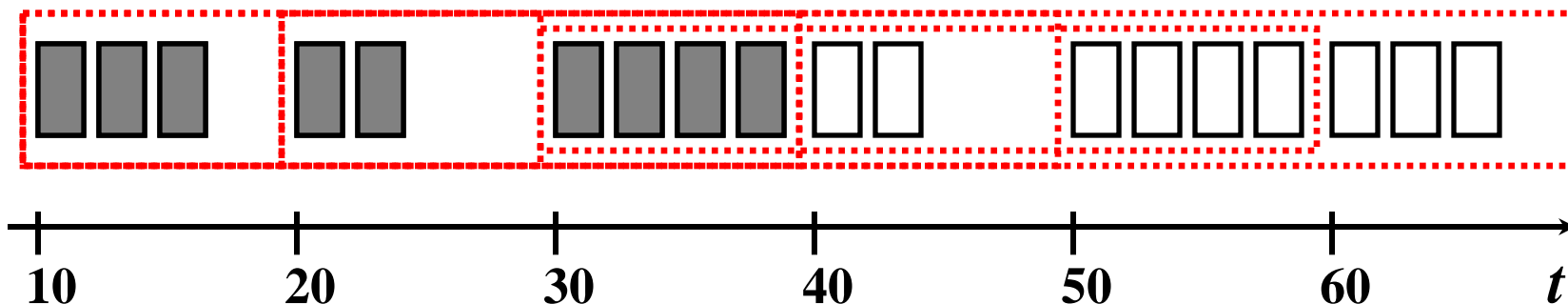
- *Windows* provide a *temporary, bounded portion* of a stream:

- Sliding • Tumbling • Partitioned • Landmark ...

- Typically *sliding windows* inherent in continuous queries:

- CQ: “*every 10 minutes*
get average temperature
over past 30 minutes”

```
SELECT AVG(S.temperature)
FROM S [RANGE 30 MINUTES
        SLIDE 10 MINUTES]
```



An “*Amnesic*” Approach

- Handling trajectories of moving objects *online*
 - Do we need all details of each historical trace?
 - Significance of each isolated position is *time-decaying*
 - Recent positions are far more important
 - Older segments may be compressed or even purged
- Introduce *multi-scale windowing* over *trajectory streams*
 - Focus on motion over *varying time horizons* in the past
 - Gradually coarser representations over greater time periods
 - Higher precision reserved for most recent segments
- Core idea extends *multi-granular windows* [TIME'10]
 - Novel “*scale*” semantics for trajectory simplification
 - Obtain generalized, comparable traces for querying
 - Convey reliable motion characteristics
 - No matter the reporting frequency from objects

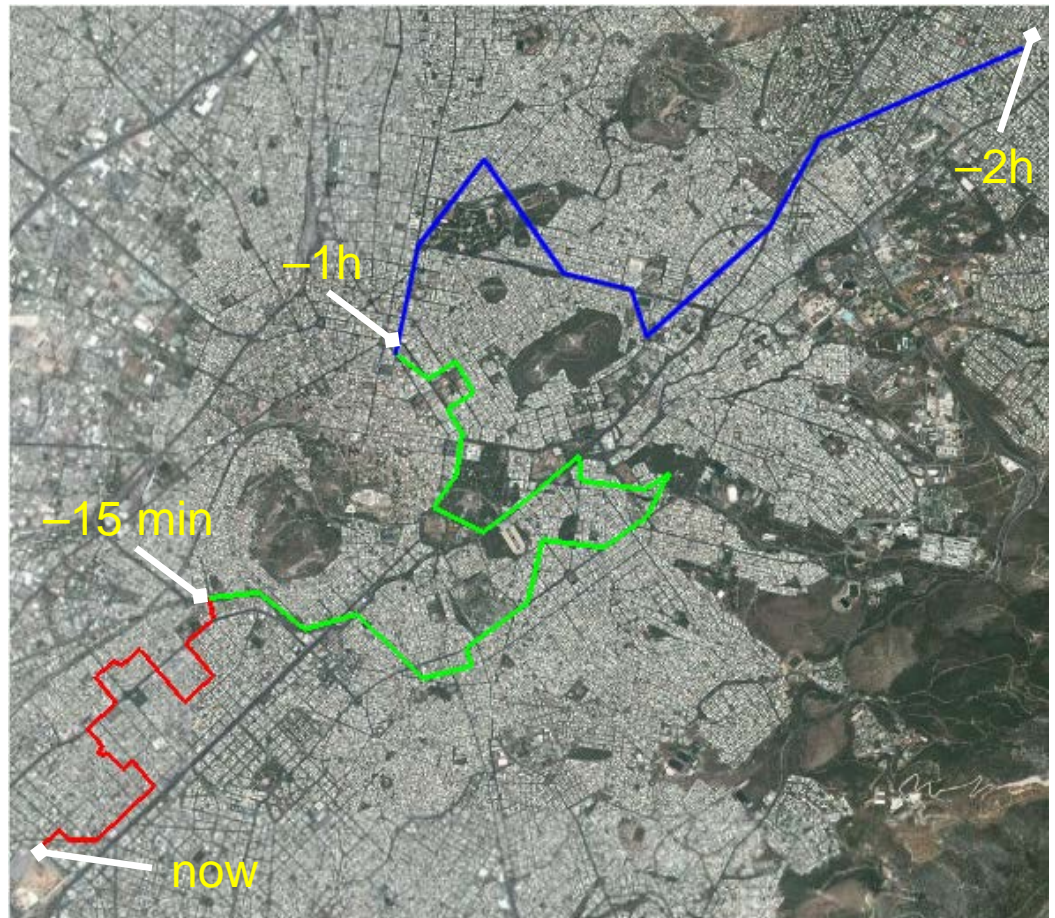
Example

- *Online simplifier per trajectory at prescribed resolutions & horizons*
- Multi-level window

RANGE 2 HOURS
SLIDE 15 MINUTES
SCALE 0.1

RANGE 1 HOUR
SLIDE 5 MINUTES
SCALE 0.3

RANGE 15 MINUTES
SLIDE 1 MINUTE
SCALE 0.5



Contribution

- Novel composite windows over trajectory streams
 - Capture essential motion features
 - Through multi-scale sliding windows
 - *With parameterized semantics in space and time*
 - Effectively “*drop detail with age*”
 - Through a user-defined “*scale*” factor
 - Ensure cohesion among trajectory segments
 - Maintenance methods for compressed representation
 - Designate *articulation points* that leave no gaps between levels
 - Specify continuous queries on trajectories
 - Applicability of typical spatiotemporal predicates
 - Expressiveness & clarity in query syntax

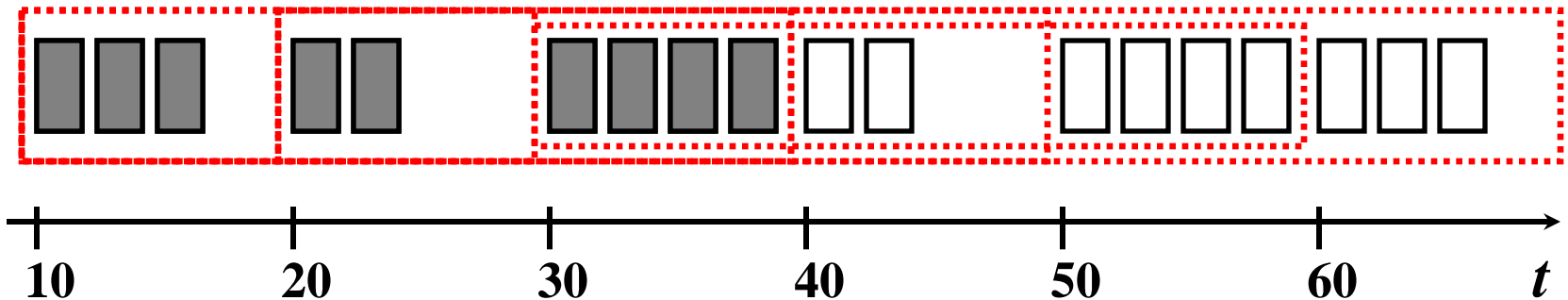
Outline

- Preliminaries: Sliding Windows *and beyond*
 - Window specifications
 - Multi-granular semantics
 - Trajectory management
- A Framework for Multi-scaling Windows
 - Model & Rationale
 - Semantics of *time*- & *trajectory*-based filtering
 - Properties
- Maintenance of Window States
 - Issues on shared & incremental computation
- Perspectives
 - Expressing windowed spatiotemporal queries
- Concluding Remarks

Time-based Sliding Windows

- Restrict stream items according to their timestamps
 - Fixed-size temporal scope ω [**RANGE:** *10 min, 1h, ...*]
 - A time interval against most recent stream items
 - Progression by slide step β [**SLIDE:** *1 sec, 5 min, ...*]
 - Stream items *expire* from the rear bound
 - *Possible overlaps*: common items between window states

➤ **EXAMPLE:** *window with $\omega = 30, \beta = 10$ time units*

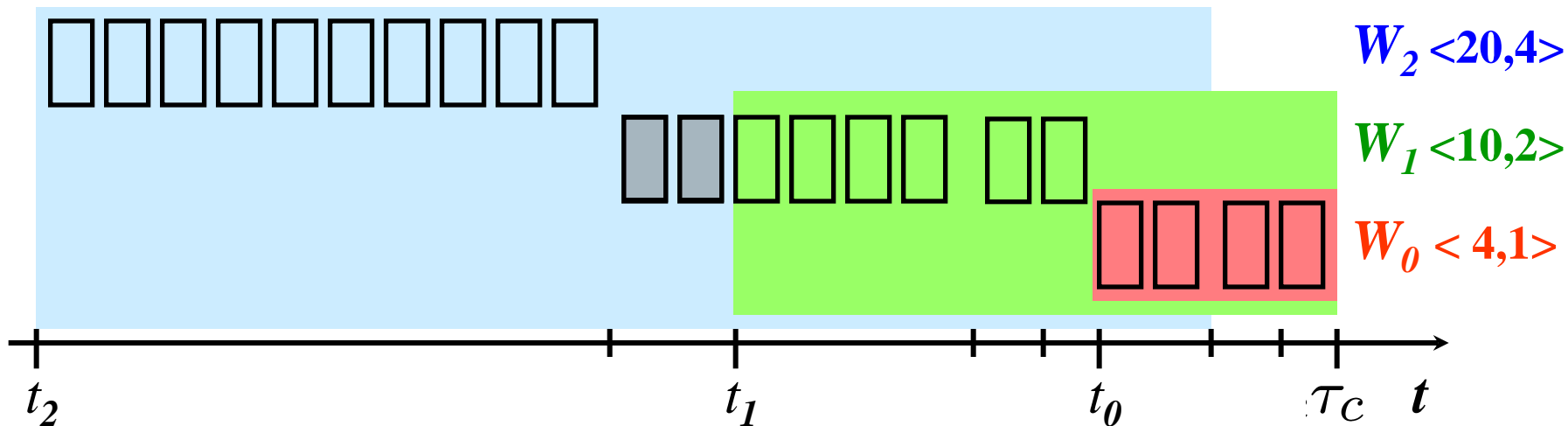


Multi-Granular Semantics

- Sliding window paradigm
 - Typically, a single timeline with all instants at similar detail
- Time implies multiple levels of resolution [LNCS 1399]
 - *seconds, minutes, hours, days*, weeks/months, years ...
 - *granule* γ_k at level k : fixed number of timestamps in \mathbb{T}
 - A set of *contiguous timestamps* – no “holes” or “gaps”
 - *Consecutive granules* at level $k \rightarrow$ a granule at $k+1$
 - Iteratively define a hierarchy with multiple levels of granularity
- Also applied to spatiotemporal modeling
 - Multi-representations by scale, time, user, point of view [InfSys'06]
 - Multi-granular types, values, conversions, queries [ICOOB'09]
- Sliding windows at *subsumable time horizons* [TIME'10]
 - Effectively, each window frame represents a granularity level

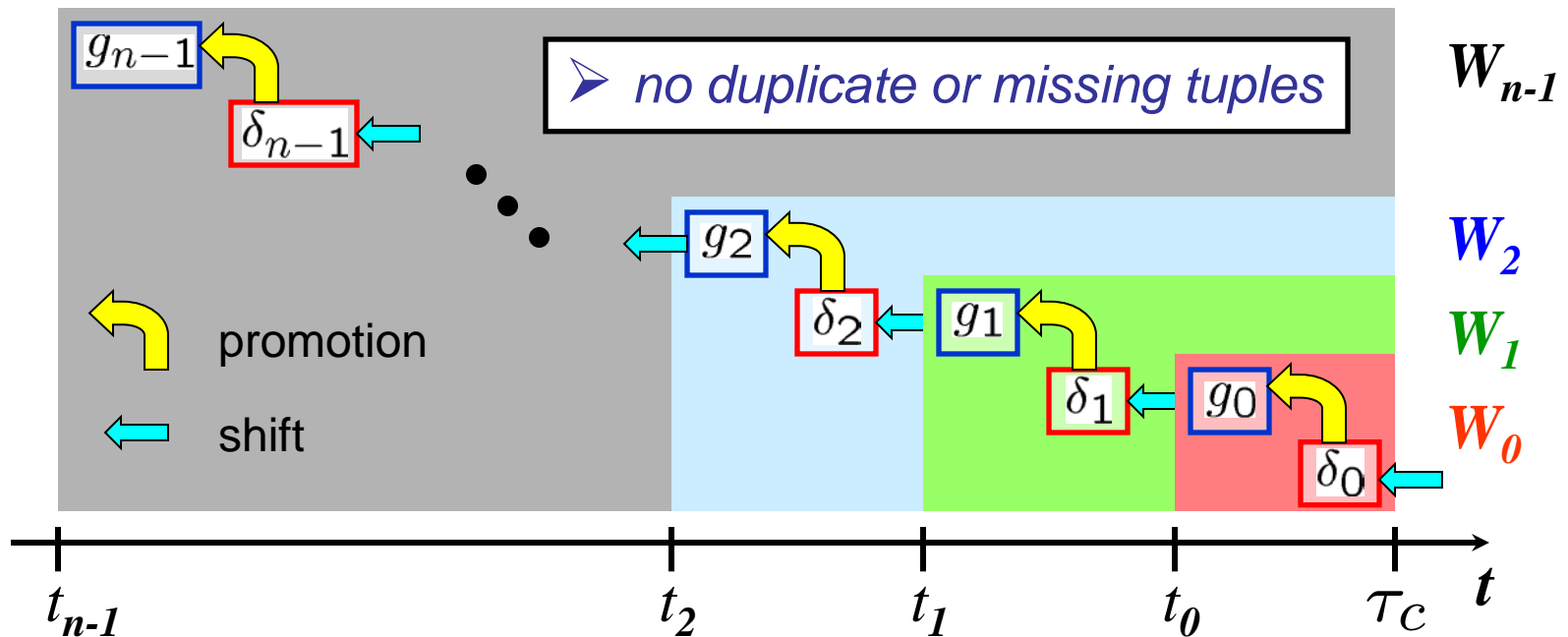
Multi-level Sliding Windows

- Window W with n levels of granularity [TIME'10]
 - At level k , subwindow W_k specifies a pair $\langle \omega_k, \beta_k \rangle$
 - RANGE** ω_k backwards from current τ_c $\omega_{k-1} < \omega_k$
 - SLIDE** forward periodically by β_k $\beta_{k-1} \leq \beta_k$
 - Hierarchy of nested frames at multiple time horizons
 - We assume a fixed number of granules per level, i.e., $\omega_k = \mu_k \cdot \beta_k$
 - Issue:** overlapping ranges may *not be synchronized* at each τ_c



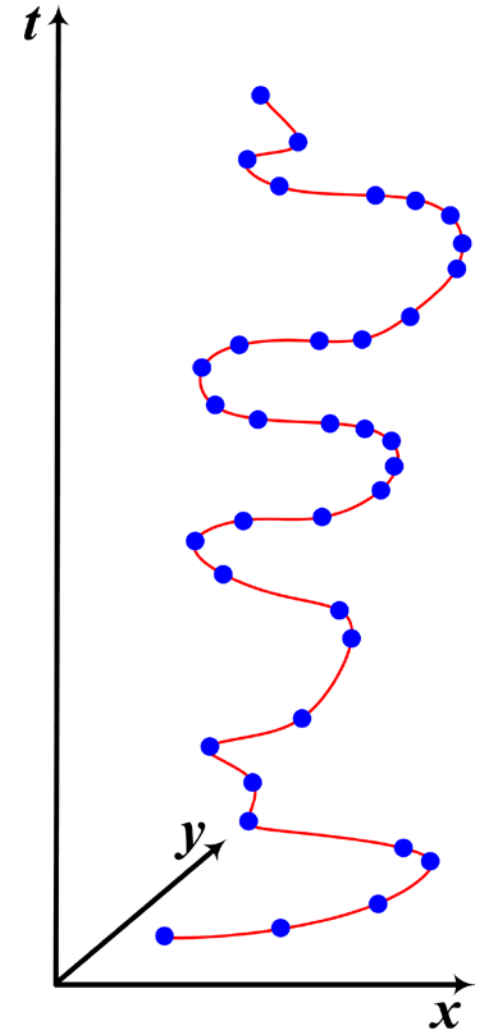
Stairwise Maintenance Scheme

- A “flight of stairs” forms a chain of *alternating*...
 - *Core nodes* g_k → queue items not covered by subordinate frames
 - *Auxiliary nodes* δ_k → buffer items expiring from a subwindow
 - Smooth maintenance: no tuples lost *in transit* between levels



Trajectory Modeling

- Monitor objects moving in a **3-d** space
 - *Positional samples* are 2-d coordinates (x,y)
 - Measured at *discrete timestamps* t
 - Expressed in primitive units (e.g., seconds)
 - Each object with known identity *id*
- Massive updates from numerous objects
 - relayed into a server at varying frequency
 - a *positional stream* of tuples $\langle id, x, y, t \rangle$
- **Trajectory** of a moving object
 - An evolving sequence of timestamped locations
 - an *append-only* collection of its GPS waypoints
 - *Ever growing traces of too much detail...*
 - Exploit *time monotonicity + windows*
 - to examine lightweight, but connected 3-d paths

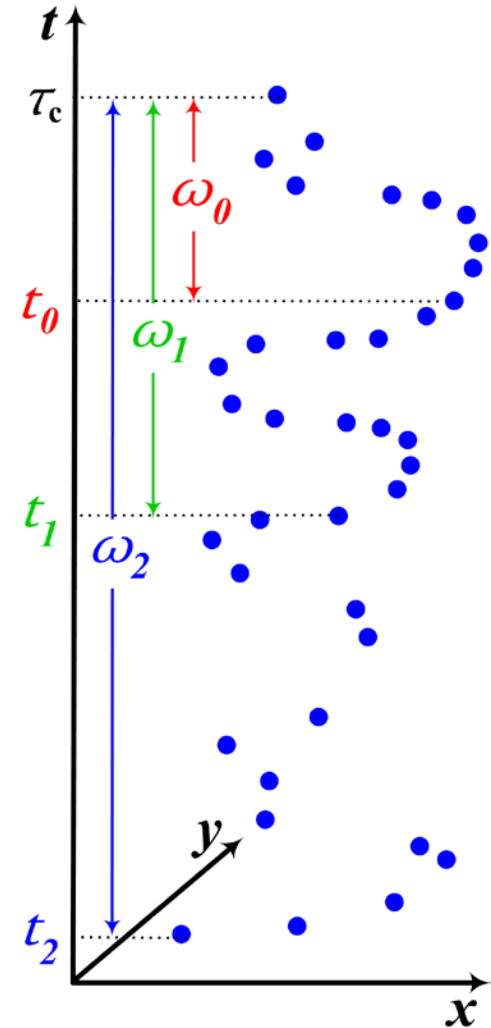


Multi-scale Window Semantics

- A window operator over streaming trajectories
 - *Time restriction* → focus on recent time periods only
 - *Data reduction* → progressively drop positions by age
 - Exploit spatial + temporal properties of trajectories
- Window is always specified by a continuous query
 - Evaluate CQ against less detailed object paths
 - *On-the-fly* trajectory compression at varying resolutions
- Operation: Filter object locations at two stages
 - *Time-based filtering*
 - Finite portions of reported locations at subsumable time intervals
 - *Trajectory-based filtering*
 - Group locations by object
 - Apply regulated generalization per trajectory at multiple scales

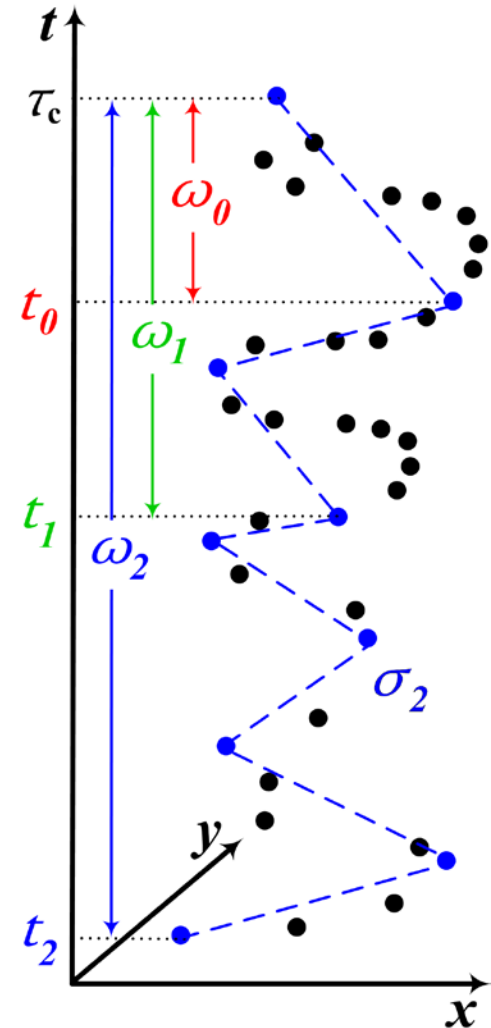
Time-based Filtering

- Retain traces over diverse time horizons
 - Each window W_k has its own specs $\langle \omega_k, \beta_k \rangle$
 - All window frames initially applied at time τ_0
 - At any $\tau_c \geq \tau_0$, each W_k has a *scope*
 - i.e., the current window *bounds*
 - [$\max\{\tau_0, \tau_c - \lambda_k - \omega_k + 1\}, \tau_c - \lambda_k$]
- Frames slide forward *discontinuously*
 - At a time-varying *lag* $\lambda_k = \text{mod}(\tau_c - \tau_0, \beta_k)$
 - Not at each timestamp or upon arrival of items
 - *Both bounds always move in tandem*
- $C_k(\tau_c)$: *Time-filtered state* per frame W_k
 - i.e., positions measured during past periods
 - last 15 min, 1 hour, 2 hours etc.



Trajectory-based Filtering

- A *demultiplexing* phase per frame W_k
 - Partition items in $\mathcal{C}_k(\tau_c)$ into distinct paths
 - $path_k(i)$: time-ordered positions per object i
 - Still, filtered data may be considerable
 - for windows with large scopes or many levels
- Maybe diverse *reporting rate* ρ_i per object
 - $\rho_i \cdot \omega_k$ locations relayed during interval ω_k
 - Randomly discard or judiciously select samples
 - Let $\delta_k^i \cdot \omega_k$ locations remain *at most*
- $\sigma_k = \frac{\delta_k^i}{\rho_i}$: *reduction ratio* applied to $path_k(i)$
 - A common *scale* $\sigma_k < 1$ per frame W_k
 - Prescribes *max detail* tolerated at each path
 - A *reduced* $path'_k(i)$ is derived



Trajectory-filtered Window States

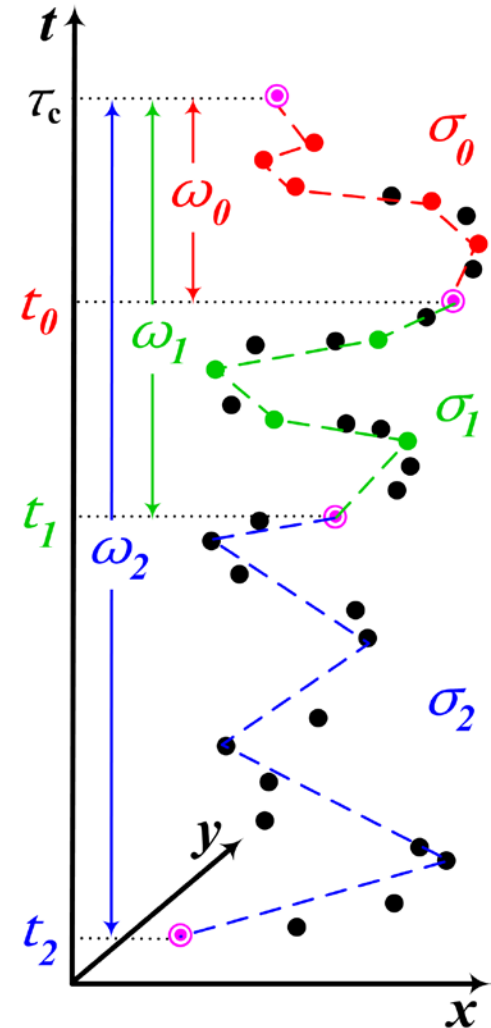
- Reduced paths do *not* have equal sample counts
 - Each trajectory is smoothed *separately*
 - but yields comparable representations
 - Derived paths are *connected* with no gaps
 - *Thanks to inherent timestamp ordering*
 - Approximate according to motion pattern & reporting frequency
 - e.g., discard superfluous points when moving along a straight path at constant speed
 - *Smaller scale $\sigma_k \rightarrow$ more approximation*
- *Trajectory-filtered state* per level W_k
 - $\mathcal{W}_k(\tau_c) = \{path'_k(i), \forall \text{ object } i\}$
 - At each scale, one compressed sequence of samples per object
 - not just dispersed timestamped locations

Discussion

- Windowing applies *to query evaluation, not storage*
 - Original trajectories do *not* become multi-granular
 - *Granules*: levels of detail for reduced paths
 - Relationships among granularities are useful
 - “*finer-than*”, “*coarser-than*” may simplify processing
 - Uniform, simple underlying data model
 - must include *position + timestamp*
 - Windows only provide *temporary paths* to queries
 - *User-defined* parameterization for **RANGE, SLIDE, SCALE**
 - Multi-scale windowing is *novel* in data stream processing
 - Distinguished from *partitioned windows*
 - Differs from *load shedding* policies
 - A “*path-creation*” step is employed to provide *sequential data*

Window Maintenance Issues

- Window-based trajectory simplification
 - A *repetitive task* due to evolving trajectories
 - *Incremental* → fresh positions are being relayed
 - *Shared* → reuse any paths already available
 - *Exploit point samples across window frames?*
 - More detailed representations closer to now
 - Fewer samples remain in coarser frames
 - Discard points upwards in window hierarchy
 - *Coordinated maintenance of multiple paths*
 - Preserve certain *articulation points* per trajectory
 - Pick samples temporally close to frame bounds
 - Minimize approximation error ~ *trajectory fitting*
 - Also a cohesive “*seamless overview*” of motion
 - non-overlapping paths joined at articulations



Trajectory Smoothing

- Alternatives for enforcing scale factor σ_k per frame W_k
 - Systematic **sampling** per trajectory
 - Start from most recent object position per frame
 - Randomly pick a sample from each successive batch of $\lceil \frac{\rho_i}{\delta_k^i} \rceil$ points
 - *Single-pass* method; may yield distorted paths
 - **Minimal distance errors**
 - Eliminate points incurring the least change in shape
 - Attain bounded space cost per level ($\sigma_k \cdot \omega_k$ locations)
 - *Multi-pass* algorithm; a Douglas-Peucker variant
 - **Online filtering at frame transitions**
 - Employ *stairwise scheme*
 - Only buffer nodes contain candidate positions for filtering
 - Drop samples when aging locations ascend through window hierarchy
 - *Inherent nesting*: no need to handle segments covered by lower frames

Windowed Queries on Trajectories

- Each window instantiation offers
 - An updated set of recent paths per monitored object
 - Contiguous traces → typical trajectories, *although approximate*
- Proposed *language constructs* to abstract data features
 - Functions returning “*timestamped polylines*”
 - **trace()**: reconstructs a separate path per subwindow
 - **trajectory()**: yields seamless synopsis from multi-scaled segments
 - Result is a sequence of locations per object
 - *Topological* operators can be applied:
 - **INTERSECTS, WITHIN, CROSSES, ...**
 - *Spatiotemporal* functions more meaningful:
 - **speed, duration, heading, distance, ...**
 - Concise *window clause* for expressiveness
 - combining **RANGE, SLIDE, SCALE** parameters for all levels

Usage of Language Constructs

- Assume a positional stream $S \langle id, pos, t \rangle$ from vehicles
 - *CQ1: Estimate average speed against varying time periods & scales*

```
SELECT AVG(speed(trace(S.pos)), WSCOPE(*))
FROM S [RANGES 1 HOUR, 15 MINUTES, 1 MINUTE
        SLIDES 5 MINUTES, 1 MINUTE, 10 SECONDS
        SCALES 0.1, 0.2, 0.5 BY S.id];
```

- *CQ2: Indicate vehicles circulating in greater Athens recently*

```
SELECT S.id, duration(trajectory(S.pos))
FROM S [RANGES 30 MINUTES, 10 MINUTES, 1 MINUTE
        SLIDES 10 MINUTES, 1 MINUTE, 15 SECONDS
        SCALES 0.1, 0.2, 0.4 BY S.id],
Cities C
WHERE trajectory(S.pos) WITHIN C.polygon
AND C.name='Athens';
```

Perspectives

- Applications
 - Fleet management
 - Traffic surveillance
 - Wildlife preservation
 - Merchandise monitoring
 - Maritime control
 - Soldier tracking ...
- Operations
 - **Trajectory filtering** for range or k -NN search
 - lightweight, synchronized trajectories at comparable scales
 - **Ageing synopses** for trajectories
 - smoothly updated, gracefully compressed
 - **Motion mining**
 - trends and patterns at varying resolutions
 - Online **multi-grained aggregates**
 - speed, heading, ... to analyze motion per trajectory
 - **Advanced visualization** on maps at diverse zoom levels

Conclusions

- Towards a foundation for a novel windowing operator
 - At multiple resolutions against streaming trajectory data
 - Semantics based on spatial + temporal properties
 - Not only restricting scope *on recent features*
 - But also progressively *dropping redundant details*
 - Opportunities for efficient shared evaluation
 - Useful in expressing spatiotemporal continuous queries
- Directions for further study
 - Incremental maintenance of multiple window states
 - *Strategies trading off performance vs. quality of approximation*
 - Verify scalability & robustness against workloads
 - *Experimentation on real / synthetic datasets*

Multi-scale Windowing over Trajectory Streams



Thank you!